



The Leray-Gårding method for finite difference schemes. II.

Smooth crossing modes

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Abstract

In Coulombel (2015) a multiplier technique, going back to Leray and Gårding for scalar hyperbolic partial differential equations, has been extended to the context of finite difference schemes for evolutionary problems. The key point of the analysis in Coulombel (2015) was to obtain a discrete energy-dissipation balance law when the initial difference operator is multiplied by a suitable quantity (the so-called multiplier). The construction of the energy and dissipation functionals was achieved in Coulombel (2015) under the assumption that all modes were separated. We relax this assumption here and construct, for the same multiplier as in Coulombel (2015), the energy and dissipation functionals when some modes cross. Semigroup estimates for fully discrete hyperbolic initial boundary value problems are deduced in this broader context.

Keywords: hyperbolic equations, difference approximations, stability, boundary conditions, semigroup estimates.

msc: 65M06, 65M12, 35L03, 35L04.

Throughout this article, we keep the same notation as in Coulombel (2015). We introduce several subsets of the complex plane \mathbb{C} :

$$\begin{aligned} \mathcal{U} &:= \{\zeta \in \mathbb{C}, |\zeta| > 1\}, & \overline{\mathcal{U}} &:= \{\zeta \in \mathbb{C}, |\zeta| \geq 1\}, \\ \mathbb{D} &:= \{\zeta \in \mathbb{C}, |\zeta| < 1\}, & \mathbb{S}^1 &:= \{\zeta \in \mathbb{C}, |\zeta| = 1\}, & \overline{\mathbb{D}} &:= \mathbb{D} \cup \mathbb{S}^1. \end{aligned}$$

We let $\mathcal{M}_n(\mathbb{K})$ denote the set of $n \times n$ matrices with entries in $\mathbb{K} = \mathbb{R}$ or \mathbb{C} . If $M \in \mathcal{M}_n(\mathbb{C})$, M^* denotes the conjugate transpose of M . We let I denote the identity matrix or the identity operator when it acts on an infinite dimensional space. We use the same notation x^*y for the Hermitian product of two vectors $x, y \in \mathbb{C}^n$ and for the Euclidean product of two vectors $x, y \in \mathbb{R}^n$. The norm of a vector $x \in \mathbb{C}^n$ is $|x| := (x^*x)^{1/2}$. The induced matrix norm on $\mathcal{M}_n(\mathbb{C})$ is denoted $\|\cdot\|$.

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The letter C denotes a constant that may vary from line to line or within the same line. The dependence of the constants on the various parameters is made precise throughout the text.

In what follows, we let $d \geq 1$ denote a fixed integer, which will stand for the dimension of the space domain we are considering. We shall use the space ℓ^2 of square integrable sequences. Sequences may be valued in \mathbb{C}^k for some integer k . Some sequences will be indexed by \mathbb{Z}^{d-1} while some will be indexed by \mathbb{Z}^d or a subset of \mathbb{Z}^d . We thus introduce some specific notation for the norms. Let $\Delta x_k > 0$ for $k = 1, \dots, d$ be d space steps as considered hereafter. We shall make use of the $\ell^2(\mathbb{Z}^{d-1})$ -norm that we define as follows: for all $v \in \ell^2(\mathbb{Z}^{d-1})$,

$$\|v\|_{\ell^2(\mathbb{Z}^{d-1})}^2 := \left(\prod_{k=2}^d \Delta x_k \right) \sum_{v=2}^d \sum_{j_v \in \mathbb{Z}} |v_{j_2, \dots, j_d}|^2.$$

The corresponding scalar product is denoted $\langle \cdot, \cdot \rangle_{\ell^2(\mathbb{Z}^{d-1})}$. Then for all integers $m_1 \leq m_2$ in \mathbb{Z} , we set

$$\| \| u \| \|_{m_1, m_2}^2 := \Delta x_1 \sum_{j_1=m_1}^{m_2} \| u_{j_1, \cdot} \|_{\ell^2(\mathbb{Z}^{d-1})}^2,$$

to denote the ℓ^2 -norm on the set $[m_1, m_2] \times \mathbb{Z}^{d-1}$ (m_1 may equal $-\infty$ and m_2 may equal $+\infty$). The corresponding scalar product is denoted $\langle \cdot, \cdot \rangle_{m_1, m_2}$. Other notation throughout the text is meant to be self-explanatory.

1 Introduction

This article is a sequel of our previous work Coulombel (2015) where we have developed a multiplier technique for finite difference schemes. The theory in Coulombel (2015) encompasses the well-known example of the leap-frog scheme for the transport equation. Our main motivation was to derive stability estimates for finite difference schemes with a method that bypasses as much as possible Fourier analysis. This was a first step towards later considering multistep time integration techniques with finite volume space discretizations on unstructured meshes. We extend the results of Coulombel (2015) by dropping a *simplicity* assumption that was made in this work, which now allows us to consider crossing eigenmodes. Namely, the situation we consider here is the one where the latter crossing occurs in a smooth way. We also completely deal with the case of multistep schemes with two time levels for which the eigenmode crossing need not be smooth. In order to avoid repeating many arguments from Coulombel (2015), we shall refer to this work whenever possible. We warn the reader that the introduction below is mostly the same as in Coulombel (2015) since the considered problem is the same and we have found it easier for the reader to recall all the assumptions needed in the proof

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of our main result (which is Theorem 1 on p. 156 below). The main difference lies in the statement of Assumption 2 below.

We now set some more notation. With $d \in \mathbb{N}^*$ being the considered space dimension, we let $\Delta x_1, \dots, \Delta x_d, \Delta t > 0$ denote the space and time steps where the ratios, also known as the so-called COURANT-FRIEDRICHS-LEWY parameters, $\lambda_k := \Delta t / \Delta x_k, k = 1, \dots, d$, are *fixed* positive constants. We keep $\Delta t \in (0, 1]$ as the only free small parameter and let the space steps $\Delta x_1, \dots, \Delta x_d$ vary accordingly. The ℓ^2 -norms with respect to the space variables have been previously defined and thus depend on Δt and the CFL parameters through the cell volume (either $\Delta x_2 \cdots \Delta x_d$ on \mathbb{Z}^{d-1} or $\Delta x_1 \cdots \Delta x_d$ on \mathbb{Z}^d). We always identify a sequence w indexed by either \mathbb{N} (for time), \mathbb{Z}^{d-1} or \mathbb{Z}^d (for space), with the corresponding step function. In particular, we shall feel free to take Fourier or Laplace transforms of such sequences.

For all index $j \in \mathbb{Z}^d$, we write $j = (j_1, j')$ with $j' := (j_2, \dots, j_d) \in \mathbb{Z}^{d-1}$. We let $p, q, r \in \mathbb{N}^d$ denote some fixed multi-integers, and define $p_1, q_1, r_1, p', q', r'$ according to the above notation. We also let $s \in \mathbb{N}$ denote some fixed integer. This article is devoted to recurrence relations of the form:

$$\begin{cases} \sum_{\sigma=0}^{s+1} Q_\sigma u_j^{n+\sigma} = \Delta t F_j^{n+s+1}, & j' \in \mathbb{Z}^{d-1}, \quad j_1 \geq 1, \quad n \geq 0, \\ u_j^{n+s+1} + \sum_{\sigma=0}^{s+1} B_{j_1, \sigma} u_{1, j'}^{n+\sigma} = g_j^{n+s+1}, & j' \in \mathbb{Z}^{d-1}, \quad j_1 = 1 - r_1, \dots, 0, \quad n \geq 0, \\ u_j^n = f_j^n, & j' \in \mathbb{Z}^{d-1}, \quad j_1 \geq 1 - r_1, \quad n = 0, \dots, s, \end{cases} \quad (1)$$

where the operators Q_σ and $B_{j_1, \sigma}$ are given by:

$$Q_\sigma := \sum_{\ell_1=-r_1}^{p_1} \sum_{\ell'=-r'}^{p'} a_{\ell, \sigma} \mathbf{S}^\ell, \quad B_{j_1, \sigma} := \sum_{\ell_1=0}^{q_1} \sum_{\ell'=-q'}^{q'} b_{\ell, j_1, \sigma} \mathbf{S}^\ell. \quad (2)$$

In (2), the $a_{\ell, \sigma}, b_{\ell, j_1, \sigma}$ are *real numbers* and are independent of the small parameter Δt (they may depend on the CFL parameters $\lambda_1, \dots, \lambda_d$ though), while \mathbf{S} denotes the shift operator on the space grid: $(\mathbf{S}^\ell v)_j := v_{j+\ell}$ for $j, \ell \in \mathbb{Z}^d$. We have also used in (2) the short notation

$$\sum_{\ell'=-r'}^{p'} := \sum_{v=2}^d \sum_{\ell_v=-r_v}^{p_v}, \quad \sum_{\ell'=-q'}^{q'} := \sum_{v=2}^d \sum_{\ell_v=-q_v}^{q_v}.$$

Namely, the operators Q_σ and $B_{j_1, \sigma}$ only act on the spatial variable $j \in \mathbb{Z}^d$, and the index σ in (1) keeps track of the dependence of (1) on the $s+2$ time levels involved at each time iteration.

The numerical scheme (1) is understood as follows: one starts with ℓ^2 initial data $(f_j^0), \dots, (f_j^s)$ defined on $[1 - r_1, +\infty) \times \mathbb{Z}^{d-1}$. The source terms (F_j^n) and (g_j^n) in (1) are given. Assuming that the solution u has been defined up to some time index

$n + s, n \geq 0$, then the first and second equations in (1) should uniquely determine u_j^{n+s+1} for $j_1 \geq 1 - r_1, j' \in \mathbb{Z}^{d-1}$. The mesh cells associated with $j_1 \geq 1$ correspond to the *interior domain* while those associated with $j_1 = 1 - r_1, \dots, 0$ represent the *discrete boundary*. Recurrence relations of the form (1) arise when considering finite difference approximations of hyperbolic initial boundary value problems², which is our main motivation (the Dirichlet and extrapolation boundary conditions³ are typical examples). We wish to deal here simultaneously with explicit and implicit schemes and therefore make the following solvability assumption.

Assumption 1 (Solvability of (1)) – The operator Q_{s+1} is an isomorphism on $\ell^2(\mathbb{Z}^d)$. Moreover, for all $F \in \ell^2(\mathbb{N}^* \times \mathbb{Z}^{d-1})$ and for all $g \in \ell^2([1 - r_1, 0] \times \mathbb{Z}^{d-1})$, there exists a unique solution $u \in \ell^2([1 - r_1, +\infty) \times \mathbb{Z}^{d-1})$ to the system

$$\begin{cases} Q_{s+1} u_j = F_j, & j' \in \mathbb{Z}^{d-1}, \quad j_1 \geq 1, \\ u_j + B_{j_1, s+1} u_{1, j'} = g_j, & j' \in \mathbb{Z}^{d-1}, \quad j_1 = 1 - r_1, \dots, 0. \end{cases}$$

The first and second equations in (1) therefore uniquely determine u_j^{n+s+1} for $j_1 \geq 1 - r_1$ and $j' \in \mathbb{Z}^{d-1}$; one then proceeds to the following time index $n + s + 2$. Existence and uniqueness of a solution (u_j^n) in $\ell^2([1 - r_1, +\infty) \times \mathbb{Z}^{d-1})^{\mathbb{N}}$ to (1) follows from Assumption 1 as long as the source terms lie in the appropriate functional spaces, so the last requirement for well-posedness is continuous dependence of the solution on the three possible source terms $(F_j^n), (g_j^n), (f_j^n)$. This is a *stability* problem for which several definitions can be chosen according to the functional framework. The following one dates back to Gustafsson, Kreiss, and Sundström (1972) in one space dimension and to Michelson (1983) in several space dimensions.

Definition 1 (Strong stability) – The finite difference approximation (1) is said to be "strongly stable" if there exists a constant C such that for all $\gamma > 0$ and all $\Delta t \in (0, 1]$, the solution (u_j^n) to (1) with zero initial data (that is, $(f_j^0) = \dots = (f_j^s) = 0$ in (1)) satisfies the estimate:

$$\begin{aligned} & \frac{\gamma}{\gamma \Delta t + 1} \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \|u^n\|_{1-r_1, +\infty}^2 + \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \sum_{j=1-r_1}^{p_1} \|u_{j_1, \cdot}^n\|_{\ell^2(\mathbb{Z}^{d-1})}^2 \quad (3) \\ & \leq C \left\{ \frac{\gamma \Delta t + 1}{\gamma} \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \|F^n\|_{1, +\infty}^2 + \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \sum_{j_1=1-r_1}^0 \|g_{j_1, \cdot}^n\|_{\ell^2(\mathbb{Z}^{d-1})}^2 \right\}. \end{aligned}$$

The main contributions in Gustafsson, Kreiss, and Sundström (1972) and Michelson (1983) are to show that strong stability can be characterized by an *algebraic*

²Gustafsson, Kreiss, and Olinger, 1995, *Time dependent problems and difference methods*.

³Coulombel and Lagoutière, 2020, "The Neumann numerical boundary condition for transport equations".

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condition which is usually referred to as the Uniform KREISS-LOPATINSKII Condition. We shall assume here from the start that (1) is strongly stable. We can thus control, for zero initial data, ℓ^2 type norms of the solution to (1). Our goal, as in Coulombel (2015), is to understand which kind of stability estimate holds for the solution to (1) when one considers *nonzero* initial data $(f_j^0), \dots, (f_j^s)$ in ℓ^2 . We are specifically interested in showing *semigroup* estimates for (1), that is in controlling the $\ell_n^\infty(\ell_j^2)$ norm of the solution to (1) (which is stronger than the $\ell_n^2(\ell_j^2)$ control encoded in (3)). Our main assumption is the following. It is a relaxed version of the corresponding assumption in Coulombel (2015) where the roots of the dispersion relation (4) below were assumed to be always simple.

Assumption 2 (Stability for the discrete Cauchy problem) – For $\kappa \in (\mathbb{C} \setminus \{0\})^d$, let us set :

$$\widehat{Q}_\sigma(\kappa) := \sum_{\ell=-r}^p \kappa^\ell a_{\ell,\sigma} \in \mathbb{C},$$

where the coefficients $a_{\ell,\sigma}$ are the same as in (2) and we use the classical notation $\kappa^\ell := \kappa_1^{\ell_1} \dots \kappa_d^{\ell_d}$ for $\kappa \in (\mathbb{C} \setminus \{0\})^d$ and $\ell \in \mathbb{Z}^d$. Then there exists a finite number of points $\underline{\kappa}^{(1)}, \dots, \underline{\kappa}^{(K)}$ in $(\mathbb{S}^1)^d$ such that the following properties hold:

- if $\kappa \in (\mathbb{S}^1)^d \setminus \{\underline{\kappa}^{(1)}, \dots, \underline{\kappa}^{(K)}\}$, the roots to the dispersion relation⁴:

$$\sum_{\sigma=0}^{s+1} \widehat{Q}_\sigma(\kappa) z^\sigma = 0, \quad (4)$$

are simple and located in \mathbb{D} .

- if κ equals one of the $\underline{\kappa}^{(k)}$'s, the dispersion relation (4) has one multiple root $\underline{z}^{(k)} \in \mathbb{D}$ (its multiplicity is denoted m_k) and all other roots are simple.
- for all $k = 1, \dots, K$, there exists a neighborhood \mathcal{V}_k of $\underline{\kappa}^{(k)}$ in \mathbb{C}^d and there exist holomorphic functions z_1, \dots, z_{m_k} on \mathcal{V}_k such that

$$z_1(\underline{\kappa}^{(k)}) = \dots = z_{m_k}(\underline{\kappa}^{(k)}) = \underline{z}^{(k)},$$

and for all $\kappa \in \mathcal{V}_k$, $z_1(\kappa), \dots, z_{m_k}(\kappa)$ are the m_k roots to (4) that are close to $\underline{z}^{(k)}$.

Assumption 2 means that the dispersion relation (4) can have multiple roots (for stability reasons⁵, multiple roots may only belong to \mathbb{D} and not to \mathbb{S}^1). When multiple roots occur, we only ask that the splitting of the multiple eigenvalue around each such point be smooth (analytic). The fact that we only consider one multiple root at

⁴From Assumption 1, we know that Q_{s+1} is an isomorphism on $\ell^2(\mathbb{Z}^d)$, which implies by Fourier analysis that $\widehat{Q}_{s+1}(\kappa)$ does not vanish for $\kappa \in (\mathbb{S}^1)^d$. In particular, the dispersion relation (4) is a polynomial equation of degree $s+1$ in z for any $\kappa \in (\mathbb{S}^1)^d$ and thus has $s+1$ roots.

⁵Gustafsson, Kreiss, and Olinger, 1995, *Time dependent problems and difference methods*.

a time is only a matter of clarity and notation. There is no doubt that more elaborate crossings (e.g., with one root remaining double along a submanifold of $(\mathbb{S}^1)^d$) could be considered by further refining the techniques developed below. Eventually, we observe that multiple roots of the dispersion relation (4) occur for instance when one uses the Adams-Bashforth or Adams-Moulton time integrators⁶ of order 3 or higher (which is the reason why extending the result of Coulombel (2015) was necessary). We now make the following assumption, which already appeared in several works⁷ on numerical boundary conditions for hyperbolic equations.

Assumption 3 (Noncharacteristic discrete boundary) – For $\ell_1 = -r_1, \dots, p_1$, $z \in \mathbb{C}$ and $\eta \in \mathbb{R}^{d-1}$, let us define

$$a_{\ell_1}(z, \eta) := \sum_{\sigma=0}^{s+1} z^\sigma \sum_{\ell'=-r'}^{p'} a_{(\ell_1, \ell'), \sigma} e^{i\ell' \cdot \eta}. \quad (5)$$

Then a_{-r_1} and a_{p_1} do not vanish on $\bar{U} \times \mathbb{R}^{d-1}$, and they have nonzero degree with respect to z for all $\eta \in \mathbb{R}^{d-1}$.

Our main result is comparable with Wu (1995, Theorem 3.3), Coulombel and Gloria (2011, Theorems 2.4 and 3.5) and Coulombel (2015). It shows that strong stability (or "GKS stability") in the sense of Definition 1 is a *sufficient* condition for incorporating ℓ^2 initial conditions in (1) and proving *optimal* semigroup estimates. Our result reads just as in Coulombel (2015) but it now holds in the broader context of Assumption 2.

Theorem 1 – Let Assumptions 1, 2 and 3 be satisfied, and assume that the scheme (1) is strongly stable in the sense of Definition 1. Then there exists a constant C such that for all $\gamma > 0$ and all $\Delta t \in (0, 1]$, the solution to (1) satisfies the estimate:

$$\begin{aligned} & \sup_{n \geq 0} e^{-2\gamma n \Delta t} \| \|u^n\| \|_{1-r_1, +\infty}^2 + \frac{\gamma}{\gamma \Delta t + 1} \sum_{n \geq 0} \Delta t e^{-2\gamma n \Delta t} \| \|u^n\| \|_{1-r_1, +\infty}^2 \\ & + \sum_{n \geq 0} \Delta t e^{-2\gamma n \Delta t} \sum_{j_1=1-r_1}^{p_1} \| \|u_{j_1}^n\| \|_{\ell^2(\mathbb{Z}^{d-1})}^2 \\ & \leq C \left\{ \sum_{\sigma=0}^s \| \|f^\sigma\| \|_{1-r_1, +\infty}^2 + \frac{\gamma \Delta t + 1}{\gamma} \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \| \|F^n\| \|_{1, +\infty}^2 \right. \\ & \quad \left. + \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \sum_{j_1=1-r_1}^0 \| \|g_{j_1}^n\| \|_{\ell^2(\mathbb{Z}^{d-1})}^2 \right\}. \quad (6) \end{aligned}$$

⁶Hairer, Nørsett, and Wanner, 1993, *Solving ordinary differential equations. I*, Chapter III.

⁷Gustafsson, Kreiss, and Sundström, 1972, "Stability theory of difference approximations for mixed initial boundary value problems. II";

Michelson, 1983, "Stability theory of difference approximations for multidimensional initial-boundary value problems".

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In particular, the scheme (1) is "semigroup stable" in the sense that there exists a constant C such that for all $\Delta t \in (0, 1]$, the solution (u_j^n) to (1) with $(F_j^n) = (g_j^n) = 0$ satisfies the estimate

$$\sup_{n \geq 0} \| \| u^n \| \|_{1-r_1, +\infty}^2 \leq C \sum_{\sigma=0}^s \| \| f^\sigma \| \|_{1-r_1, +\infty}^2. \quad (7)$$

The scheme (1) is also ℓ^2 -stable with respect to boundary data, see Trefethen (1984, Definition 4.5), in the sense that there exists a constant C such that for all $\Delta t \in (0, 1]$, the solution (u_j^n) to (1) with $(F_j^n) = (f_j^n) = 0$ satisfies the estimate

$$\sup_{n \geq 0} \| \| u^n \| \|_{1-r_1, +\infty}^2 \leq C \sum_{n \geq s+1} \Delta t \sum_{j_1=1-r_1}^0 \| g_{j_1}^n \|_{\ell^2(\mathbb{Z}^{d-1})}^2.$$

Multiplier techniques have been developed in the study of A -stability (or $A(\alpha)$ -stability) for multistep integrators, see for instance Nevanlinna and Odeh (1981) and Akrivis and Katsoprinakis (2016). Such techniques are used, for instance in the proof of Dahlquist's equivalence theorem of A - and G -stability⁸. One typical example of multistep integrator for which a (very simple !) multiplier is known is the BDF-2 method⁹. It turns out that our multiplier technique is not restricted to A -stable methods, though some of the details below look similar to the theory in Nevanlinna and Odeh (1981). We shall try to explore more into such possible connections in the future.

Sections 2 and 3 below are devoted to the proof of Theorem 1. We follow the lines of Coulombel (2015) and first explain why the same multiplier yields an energy-dissipation balance law for the Cauchy problem (in the whole space) in the broader framework of Assumption 2. The analysis relies on a suitable construction of the energy and dissipation functionals, which are more involved than in Coulombel (2015). The end of the proof of Theorem 1 follows Coulombel (2015) almost word for word. We explain where the specificity of the broader framework of Assumption 2 comes into play. In an Appendix, we deal with the specific case $s = 1$ (recurrence relations with two time levels) for which energy and dissipation functionals with *local densities* can be constructed. This gives hope to later deal with finite volume space discretization techniques on unstructured meshes.

⁸Hairer and Wanner, 1996, *Solving ordinary differential equations. II*, Chapter V.6.

⁹Emmrich, 2009a, "Convergence of the variable two-step BDF time discretisation of nonlinear evolution problems governed by a monotone potential operator";

Emmrich, 2009b, "Two-step BDF time discretisation of nonlinear evolution problems governed by monotone operators with strongly continuous perturbations".

2 The Leray-Gårding method for fully discrete Cauchy problems

This section is devoted to proving stability estimates for discretized Cauchy problems in the whole space \mathbb{Z}^d , which is the first step before considering the discretized initial boundary value problem (1). More precisely, we consider the simpler case of the whole space $j \in \mathbb{Z}^d$, and the recurrence relation in $\ell^2(\mathbb{Z}^d)$:

$$\begin{cases} \sum_{\sigma=0}^{s+1} Q_\sigma u_j^{n+\sigma} = 0, & j \in \mathbb{Z}^d, \quad n \geq 0, \\ u_j^n = f_j^n, & j \in \mathbb{Z}^d, \quad n = 0, \dots, s, \end{cases} \quad (8)$$

where the operators Q_σ are given by (2). We recall that in (2), the $a_{\ell,\sigma}$ are real numbers and are independent of the small parameter Δt (they may depend on the CFL parameters $\lambda_1, \dots, \lambda_d$), while \mathbf{S} denotes the shift operator on the space grid: $(\mathbf{S}^\ell v)_j := v_{j+\ell}$ for $j, \ell \in \mathbb{Z}^d$. Stability of (8) is defined as follows.

Definition 2 (Stability for the discrete Cauchy problem) – The numerical scheme (8) is (ℓ^2 -) stable if Q_{s+1} is an isomorphism from $\ell^2(\mathbb{Z}^d)$ onto itself, and if furthermore there exists a constant $C_0 > 0$ such that for all $\Delta t \in (0, 1]$, for all initial conditions $f^0, \dots, f^s \in \ell^2(\mathbb{Z}^d)$, there holds

$$\sup_{n \in \mathbb{N}} \| \| u^n \| \|_{-\infty, +\infty}^2 \leq C_0 \sum_{\sigma=0}^s \| \| f^\sigma \| \|_{-\infty, +\infty}^2. \quad (9)$$

Let us quickly recall, see e.g. Gustafsson, Kreiss, and Olinger (1995), that stability in the sense of Definition 2 is in fact independent of $\Delta t \in (0, 1]$ (because (8) nowhere involves Δt and the norms in (9) can be simplified on either side by the cell volume $\prod_k \Delta x_k$), and can be characterized in terms of the uniform power boundedness of the so-called amplification matrix

$$\mathcal{A}(\kappa) := \begin{bmatrix} -\widehat{Q}_s(\kappa)/\widehat{Q}_{s+1}(\kappa) & \dots & \dots & -\widehat{Q}_0(\kappa)/\widehat{Q}_{s+1}(\kappa) \\ 1 & 0 & \dots & 0 \\ 0 & \ddots & \ddots & \vdots \\ 0 & 0 & 1 & 0 \end{bmatrix} \in \mathcal{M}_{s+1}(\mathbb{C}), \quad (10)$$

where the $\widehat{Q}_\sigma(\kappa)$'s are defined in (4) and where it is understood that \mathcal{A} is defined on the largest open set of \mathbb{C}^d on which \widehat{Q}_{s+1} does not vanish. Let us also recall that if Q_{s+1} is an isomorphism from $\ell^2(\mathbb{Z}^d)$ onto itself, then \widehat{Q}_{s+1} does not vanish on $(\mathbb{S}^1)^d$, and therefore does not vanish on an open neighborhood of $(\mathbb{S}^1)^d$. With the above definition (10) for \mathcal{A} , the following well-known result holds, see e.g. Gustafsson, Kreiss, and Olinger (1995):

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Proposition 1 (Stability for discrete Cauchy problems) – Assume that the operator Q_{s+1} is an isomorphism from $\ell^2(\mathbb{Z}^d)$ onto itself. Then the scheme (8) is stable in the sense of Definition 2 if and only if there exists a constant $C_1 > 0$ such that the amplification matrix \mathcal{A} in (10) satisfies

$$\forall n \in \mathbb{N}, \quad \forall \kappa \in (\mathbb{S}^1)^d, \quad \|\mathcal{A}(\kappa)^n\| \leq C_1. \quad (11)$$

In particular, the spectral radius of $\mathcal{A}(\kappa)$ should not be larger than 1 (the so-called von Neumann condition).

The eigenvalues of $\mathcal{A}(\kappa)$ are the roots to the dispersion relation (4). When these roots are simple for all $\kappa \in (\mathbb{S}^1)^d$, the von Neumann condition is both necessary and sufficient for stability of (8), see, e.g., Coulombel (2013, Proposition 3). However, Assumption 2 is more general than the situation considered in Coulombel (2015) where the roots always remain simple. Nevertheless, since the occurrence of a multiple root only occurs in the interior \mathbb{D} and not on the boundary \mathbb{S}^1 , we easily deduce from Assumption 2 that the matrix $\mathcal{A}(\kappa)$ in (10) is *geometrically regular* in the sense of Coulombel (2013, Definition 3). Hence we can still apply Coulombel (2013, Proposition 3) and conclude that Assumption 2 implies stability for the Cauchy problem (8) (in the sense of Definition 2). As in Coulombel (2015), our goal now is to derive the semigroup estimate (9) not by applying Fourier transform to (8) and using uniform power boundedness of \mathcal{A} , but rather by multiplying the first equation in (8) by a suitable *local* multiplier. As a warm-up, and to make things as clear as possible, we first deal with the simpler case where one only considers the time evolution and no additional space variable (the standard recurrence relations in \mathbb{C}).

2.1 Stable recurrence relations

In this paragraph, we consider sequences $(v^n)_{n \in \mathbb{N}}$ with values in \mathbb{C} . The index n should be thought of as the discrete time variable, which is the reason why we always write n as an exponent in order to be consistent with the notation used for discretized partial differential equations. Let then $\nu \geq 1$ and let a_ν, \dots, a_0 be some complex numbers with $a_\nu \neq 0$ (in the next Paragraphs, we choose $\nu = s + 1$). It is well known that all solutions $(v^n)_{n \in \mathbb{N}}$ to the recurrence relation

$$\forall n \in \mathbb{N}, \quad a_\nu v^{n+\nu} + \dots + a_0 v^n = 0,$$

are bounded if and only if the polynomial:

$$\mathbb{P}(X) := a_\nu X^\nu + \dots + a_1 X + a_0, \quad (12)$$

has all its roots in $\overline{\mathbb{D}}$ and the roots on \mathbb{S}^1 are simple, see Hairer, Nørsett, and Wanner (1993, chapter III.3). This is equivalent to requiring that the companion matrix

(compare with (10)):

$$\begin{bmatrix} -a_{v-1}/a_v & \dots & \dots & -a_0/a_v \\ 1 & 0 & \dots & 0 \\ 0 & \ddots & \ddots & \vdots \\ 0 & 0 & 1 & 0 \end{bmatrix} \in \mathcal{M}_v(\mathbb{C}),$$

be power bounded. In that case, the Kreiss matrix Theorem Strikwerda and Wade (1997) implies that the latter matrix is a contraction (it has a norm ≤ 1) for some Hermitian norm on \mathbb{C}^v . In Coulombel (2015), we have obtained some explicit construction of such a Hermitian norm and an associated dissipation functional in the case where *all the roots* of \mathbb{P} in (12) are *simple* and located in $\overline{\mathbb{D}}$. The construction is based on a multiplier technique which is the discrete analogue of Gårding (1956, Lemme 1.1). The inconvenience of the result in Coulombel (2015) is that even the roots in \mathbb{D} , which are associated with an exponentially decaying behavior in time, are assumed to be simple. We suppress this technical assumption here and explain why the multiplier technique developed in Coulombel (2015) allows to deal with the general case with multiple roots in \mathbb{D} .

As in Coulombel (2015), we introduce the notation \mathbf{T} for the shift operator in time, that is, for any sequence $(v^n)_{n \in \mathbb{N}}$, we define: $(\mathbf{T}^m v)^n := v^{n+m}$ for all $m, n \in \mathbb{N}$. The following Lemma is an extension of Coulombel (2015, Lemma 1).

Lemma 1 (The energy-dissipation balance law for recurrence relations) – *Let $P \in \mathbb{C}[X]$ be a polynomial of degree v , $v \geq 1$, that satisfies the following two properties:*

- *If $P(z) = 0$, then $z \in \overline{\mathbb{D}}$.*
- *If $P(z) = 0$ and $z \in \mathbb{S}^1$, then z is a simple root of P .*

Then there exists a positive definite Hermitian form q_e on \mathbb{C}^v , and a nonnegative Hermitian form q_d on \mathbb{C}^v such that for any sequence $(v^n)_{n \in \mathbb{N}}$ with values in \mathbb{C} , there holds:

$$\begin{aligned} \forall n \in \mathbb{N}, \quad & 2\operatorname{Re}\left(\overline{\mathbf{T}(P'(\mathbf{T})v^n)}P(\mathbf{T})v^n\right) \\ & = v|P(\mathbf{T})v^n|^2 + (\mathbf{T} - I)\left(q_e(v^n, \dots, v^{n+v-1})\right) + q_d(v^n, \dots, v^{n+v-1}). \end{aligned}$$

In particular, for any sequence $(v^n)_{n \in \mathbb{N}}$ that satisfies the recurrence relation

$$\forall n \in \mathbb{N}, \quad P(\mathbf{T})v^n = 0,$$

the sequence $(q_e(v^n, \dots, v^{n+v-1}))_{n \in \mathbb{N}}$ is nonincreasing.

The multiplier $\mathbf{T}P'(\mathbf{T})v^n$ used in Lemma 1 is the same as in Coulombel (2015). We shall see below in the proof why the expressions provided in Coulombel (2015) for the energy and dissipation functions q_e, q_d can not cover the case of multiple roots and how they should be modified.

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Proof. Let us first recall the proof in Coulombel (2015) in the case of *simple* roots because this is the starting point for the general case we consider here. We therefore assume for now that P has degree ν and only has simple roots z_1, \dots, z_ν located in $\overline{\mathbb{D}}$. We write

$$P(X) = a \prod_{j=1}^{\nu} (X - z_j),$$

with $a \neq 0$, and introduce the Lagrange polynomials:

$$\forall k = 1, \dots, \nu, \quad P_k(X) := a \prod_{\substack{j=1 \\ j \neq k}}^{\nu} (X - z_j).$$

Since the z_j 's are pairwise distinct, the P_k 's form a basis of $\mathbb{C}_{\nu-1}[X]$. Moreover, the following relation was obtained in Coulombel (2015):

$$\begin{aligned} & 2\operatorname{Re}\left(\overline{\mathbf{T}(P'(\mathbf{T})v^n)}P(\mathbf{T})v^n\right) - \nu|P(\mathbf{T})v^n|^2 \\ &= (\mathbf{T} - I) \left\{ \sum_{k=1}^{\nu} |P_k(\mathbf{T})v^n|^2 \right\} + \sum_{k=1}^{\nu} (1 - |z_k|^2) |P_k(\mathbf{T})v^n|^2. \end{aligned} \quad (13)$$

The conclusion of Lemma 1 is then obtained by introducing the energy (q_e) and dissipation (q_d) forms:

$$\forall (w^0, \dots, w^{\nu-1}) \in \mathbb{C}^\nu, \quad q_e(w^0, \dots, w^{\nu-1}) := \sum_{k=1}^{\nu} |P_k(\mathbf{T})w^0|^2, \quad (14)$$

$$q_d(w^0, \dots, w^{\nu-1}) := \sum_{k=1}^{\nu} (1 - |z_k|^2) |P_k(\mathbf{T})w^0|^2. \quad (15)$$

When the roots of P are located in $\overline{\mathbb{D}}$, q_d is obviously nonnegative (this property does not depend on the fact that the roots are simple). When furthermore the roots of P are simple, the P_k 's form a basis of $\mathbb{C}_{\nu-1}[X]$ and q_e is positive definite. The conclusion follows.

We now turn to the general case and therefore no longer assume that the roots of P in \mathbb{D} are simple. For the sake of clarity, we label the pairwise distinct roots of P as z_1, \dots, z_m and let μ_1, \dots, μ_m denote the corresponding multiplicities. We thus have:

$$P(X) = a \prod_{j=1}^m (X - z_j)^{\mu_j},$$

for some $a \neq 0$, and we introduce the polynomials:

$$\forall k = 1, \dots, m, \quad P_k(X) := a(X - z_k)^{\mu_k - 1} \prod_{\substack{j=1 \\ j \neq k}}^m (X - z_j)^{\mu_j}.$$

We thus get the relation:

$$P' = \sum_{k=1}^m \mu_k P_k,$$

and it is a simple exercise to adapt the computation in Coulombel (2015) to obtain the relation (compare with (13)):

$$\begin{aligned} & 2\operatorname{Re}\left(\overline{\mathbf{T}(P'(\mathbf{T})v^n)}P(\mathbf{T})v^n\right) - \nu|P(\mathbf{T})v^n|^2 \\ &= (\mathbf{T} - I) \left\{ \sum_{k=1}^m \mu_k |P_k(\mathbf{T})v^n|^2 \right\} + \sum_{k=1}^m \mu_k (1 - |z_k|^2) |P_k(\mathbf{T})v^n|^2. \end{aligned} \quad (16)$$

The problem which we are facing is that there are too few polynomials P_k to span the whole space $\mathbb{C}_{\nu-1}[X]$. The trick consists in adding to the energy part on the right hand side of (16) some nonnegative Hermitian forms in order to gain positive definiteness, while still keeping the corresponding dissipation form nonnegative. This “add and subtract” trick is performed below.

As long as a root z_k is at least double ($\mu_k \geq 2$), we introduce the polynomials:

$$\forall j = 1, \dots, \mu_k - 1, \quad Q_{k,j}(X) := a(X - z_k)^{j-1} \prod_{\substack{\ell=1 \\ \ell \neq k}}^m (X - z_\ell)^{\mu_\ell},$$

each of which being of degree $\leq \nu - 2$. (Later we shall use the fact that $XQ_{k,j}(X)$ has degree $\leq \nu - 1$.) We go back to (16) and add/subtract suitable quantities as follows:

$$\begin{aligned} & 2\operatorname{Re}\left(\overline{\mathbf{T}(P'(\mathbf{T})v^n)}P(\mathbf{T})v^n\right) - \nu|P(\mathbf{T})v^n|^2 \\ &= (\mathbf{T} - I) \left\{ \sum_{k=1}^m \mu_k |P_k(\mathbf{T})v^n|^2 + \sum_{k=1}^m \sum_{j=1}^{\mu_k - 1} \varepsilon^{\mu_k - j} (1 - |z_k|^2)^{2(\mu_k - j)} |Q_{k,j}(\mathbf{T})v^n|^2 \right\} \\ &+ \sum_{k=1}^m \mu_k (1 - |z_k|^2) |P_k(\mathbf{T})v^n|^2 \\ &+ \sum_{k=1}^m \sum_{j=1}^{\mu_k - 1} \varepsilon^{\mu_k - j} (1 - |z_k|^2)^{2(\mu_k - j)} \left(|Q_{k,j}(\mathbf{T})v^n|^2 - |Q_{k,j}(\mathbf{T})v^{n+1}|^2 \right), \end{aligned} \quad (17)$$

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where $\varepsilon > 0$ is a parameter to be fixed later on (any choice $0 < \varepsilon \leq 1/4$ will do). In (17), it is understood that if $\mu_k = 1$ (that is, if the root z_k is simple), then we do not add any polynomial $Q_{k,j}$, the range of indices $1 \leq j \leq \mu_k - 1$ being empty. Moreover, we recall that if $\mu_k \geq 2$ for some k , then we have $|z_k| < 1$ so the coefficient of the Hermitian form $|Q_{k,j}(\mathbf{T})w^0|^2$ on the second line of (17) will be positive.

It remains to show that for some suitably chosen parameter $\varepsilon > 0$, the decomposition (17) yields the result of Lemma 1. Let us first observe that the ν polynomials

$$Q_{1,1}, \dots, Q_{1,\mu_1-1}, P_1, \dots, Q_{m,1}, \dots, Q_{m,\mu_m-1}, P_m,$$

span the space $\mathbb{C}_{\nu-1}[X]$ (this is nothing but the classical Hermite interpolation problem). Since the quantity $1 - |z_k|^2$ is positive as long as μ_k is larger than 2, any choice $\varepsilon > 0$ will make the Hermitian form q_e defined on \mathbb{C}^ν by:

$$\begin{aligned} \forall (w^0, \dots, w^{\nu-1}) \in \mathbb{C}^\nu, \\ q_e(w^0, \dots, w^{\nu-1}) := \sum_{k=1}^m \mu_k |P_k(\mathbf{T})w^0|^2 \\ + \sum_{k=1}^m \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} |Q_{k,j}(\mathbf{T})w^0|^2, \end{aligned} \quad (18)$$

positive definite. We thus now define a Hermitian form q_d on \mathbb{C}^ν by:

$$\begin{aligned} \forall (w^0, \dots, w^{\nu-1}) \in \mathbb{C}^\nu, \\ q_d(w^0, \dots, w^{\nu-1}) := \sum_{k=1}^m \mu_k (1 - |z_k|^2) |P_k(\mathbf{T})w^0|^2 \\ + \sum_{k=1}^m \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} (|Q_{k,j}(\mathbf{T})w^0|^2 - |Q_{k,j}(\mathbf{T})w^1|^2), \end{aligned} \quad (19)$$

and we are going to show that a convenient choice of ε makes q_d nonnegative. (Let us observe here that it is crucial to have the degree of $Q_{k,j}$ less than $\nu - 2$ so that the quantity $Q_{k,j}(\mathbf{T})w^1$ is a linear combination of $w^1, \dots, w^{\nu-1}$.) With the above definitions (18) and (19) for q_e and q_d , the energy balance law (17) reads as claimed in Lemma 1, so the only remaining task is to show that q_d is nonnegative for a convenient choice of $\varepsilon > 0$.

We use below the convention $Q_{k,\mu_k} := P_k$, which is compatible with the above definition of P_k and of the $Q_{k,j}$'s. Observing that there holds:

$$\forall j = 1, \dots, \mu_k - 1, \quad XQ_{k,j}(X) = Q_{k,j+1} + z_k Q_{k,j},$$

we have for any $k = 1, \dots, m$:

$$\begin{aligned}
 & \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} \left(|Q_{k,j}(\mathbf{T})w^0|^2 - |Q_{k,j}(\mathbf{T})w^1|^2 \right) \\
 &= \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} \left(|Q_{k,j}(\mathbf{T})w^0|^2 - |Q_{k,j+1}(\mathbf{T})w^0 + z_k Q_{k,j}(\mathbf{T})w^0|^2 \right) \\
 &= \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} \left((1 - |z_k|^2) |Q_{k,j}(\mathbf{T})w^0|^2 - |Q_{k,j+1}(\mathbf{T})w^0|^2 \right) \\
 &\quad - \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} 2\operatorname{Re} \left(\overline{z_k Q_{k,j}(\mathbf{T})w^0} Q_{k,j+1}(\mathbf{T})w^0 \right).
 \end{aligned}$$

We use Young's inequality as follows:

$$\begin{aligned}
 & \left| 2\operatorname{Re} \left(\overline{z_k Q_{k,j}(\mathbf{T})w^0} Q_{k,j+1}(\mathbf{T})w^0 \right) \right| \\
 & \leq \frac{1}{2} (1 - |z_k|^2) |Q_{k,j}(\mathbf{T})w^0|^2 + \frac{2|z_k|^2}{1 - |z_k|^2} |Q_{k,j+1}(\mathbf{T})w^0|^2,
 \end{aligned}$$

and thus derive the lower bound:

$$\begin{aligned}
 & \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} \left(|Q_{k,j}(\mathbf{T})w^0|^2 - |Q_{k,j}(\mathbf{T})w^1|^2 \right) \\
 & \geq \sum_{j=1}^{\mu_k-1} \frac{1}{2} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)+1} |Q_{k,j}(\mathbf{T})w^0|^2 \\
 & \quad - \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} \frac{1 + |z_k|^2}{1 - |z_k|^2} |Q_{k,j+1}(\mathbf{T})w^0|^2.
 \end{aligned}$$

Shifting indices, we get:

$$\begin{aligned}
 & \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} \left(|Q_{k,j}(\mathbf{T})w^0|^2 - |Q_{k,j}(\mathbf{T})w^1|^2 \right) \\
 & \geq \sum_{j=0}^{\mu_k-2} \frac{1}{2\varepsilon} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)-1} |Q_{k,j+1}(\mathbf{T})w^0|^2 \\
 & \quad - \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} \frac{1 + |z_k|^2}{1 - |z_k|^2} |Q_{k,j+1}(\mathbf{T})w^0|^2.
 \end{aligned}$$

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Restricting from now on to $0 < \varepsilon \leq 1/4$, we have $1/(2\varepsilon) \geq 2 \geq 1 + |z_k|^2$ and all terms corresponding to the indices $j = 1, \dots, \mu_k - 2$ in the above two sums match to give a nonnegative quantity (the first one for $j = 0$ obviously gives a nonnegative contribution since it only appears in the first sum). Hence we can keep only the very last term corresponding to $j = \mu_k - 1$ and we have thus derived the lower bound:

$$\begin{aligned} & \sum_{j=1}^{\mu_k-1} \varepsilon^{\mu_k-j} (1 - |z_k|^2)^{2(\mu_k-j)} \left(|Q_{k,j}(\mathbf{T})w^0|^2 - |Q_{k,j}(\mathbf{T})w^1|^2 \right) \\ & \geq -\varepsilon(1 - |z_k|^2)(1 + |z_k|^2) |Q_{k,\mu_k}(\mathbf{T})w^0|^2 \geq -\frac{1}{2}(1 - |z_k|^2) |P_k(\mathbf{T})w^0|^2, \end{aligned}$$

where we have used $|z_k| \leq 1$ and $\varepsilon \leq 1/4$ in the last inequality. Going back to the definition (19) of q_d , and summing over the k 's, we obtain that the Hermitian form q_d is nonnegative for any choice of ε within the interval $(0, 1/4]$. The proof of Lemma 1 is complete. \square

2.2 The energy-dissipation balance for finite difference schemes

In this paragraph, we consider the numerical scheme (8). We introduce the following notation:

$$L := \sum_{\sigma=0}^{s+1} \mathbf{T}^\sigma Q_\sigma, \quad M := \sum_{\sigma=0}^{s+1} \sigma \mathbf{T}^\sigma Q_\sigma. \quad (20)$$

Thanks to Fourier analysis, the following result will be a consequence of Lemma 1.

Proposition 2 (Energy-dissipation for finite difference schemes) – *Let Assumptions 1 and 2 be satisfied. Then there exist a continuous coercive quadratic form E and a continuous nonnegative quadratic form D on $\ell^2(\mathbb{Z}^d; \mathbb{R})^{s+1}$ such that for all sequences $(v^n)_{n \in \mathbb{N}}$ with values in $\ell^2(\mathbb{Z}^d; \mathbb{R})$ and for all $n \in \mathbb{N}$, there holds*

$$2\langle Mv^n, Lv^n \rangle_{-\infty, +\infty} = (s+1) \|Lv^n\|_{-\infty, +\infty}^2 + (\mathbf{T}-I)E(v^n, \dots, v^{n+s}) + D(v^n, \dots, v^{n+s}).$$

In particular, for any choice of initial data $f^0, \dots, f^s \in \ell^2(\mathbb{Z}^d; \mathbb{R})$, the solution to (8) satisfies

$$\sup_{n \in \mathbb{N}} E(u^n, \dots, u^{n+s}) \leq E(f^0, \dots, f^s),$$

and (8) is (ℓ^2) -stable.

Proof. We use the same notation v^n for the sequence $(v_j^n)_{j \in \mathbb{Z}^d}$ and the corresponding step function on \mathbb{R}^d whose value on the cell $[j_1 \Delta x_1, (j_1 + 1) \Delta x_1) \times \dots \times [j_d \Delta x_d, (j_d + 1) \Delta x_d)$ equals v_j^n for any $j \in \mathbb{Z}^d$. Then Plancherel's Theorem gives the identity

$$\begin{aligned} & 2\langle Mv^n, Lv^n \rangle_{-\infty, +\infty} - (s+1) \|Lv^n\|_{-\infty, +\infty}^2 \\ & = \int_{\mathbb{R}^d} 2\operatorname{Re} \left(\overline{\mathbf{T}(P'_k(\mathbf{T})\widehat{v}^n(\xi))} P_k(\mathbf{T})\widehat{v}^n(\xi) \right) - (s+1) |P_k(\mathbf{T})\widehat{v}^n(\xi)|^2 \frac{d\xi}{(2\pi)^d}, \quad (21) \end{aligned}$$

where \widehat{v}^n denotes the Fourier transform (in $L^2(\mathbb{R}^d)$) of the function v^n , and where we have let

$$P_\kappa(z) := \sum_{\sigma=0}^{s+1} \widehat{Q}_\sigma(\kappa_1, \dots, \kappa_d) z^\sigma, \quad \kappa_j := e^{i\xi_j \Delta x_j} \in \mathbb{S}^1,$$

and $P'_\kappa(z)$ denotes the derivative of P_κ with respect to z .

The construction of the quadratic forms E and D is made, as in Coulombel (2015), of the superposition of appropriate energy and dissipation Hermitian forms for each frequency $\kappa \in (\mathbb{S}^1)^d$, each coordinate κ_j being a placeholder for $\exp(i\xi_j \Delta x_j)$. Here, unlike Coulombel (2015), the polynomial P_κ either only has simple roots in $\overline{\mathbb{D}}$ or it has one multiple root in \mathbb{D} and all other roots are simple. We cannot therefore construct the energy and dissipation forms in a unified manner. Below we shall use the analysis of Lemma 1 in the neighborhood of finitely many points in $(\mathbb{S}^1)^d$ where P_κ has a multiple root and we shall use Coulombel (2015, Lemma 1) in the neighborhood of all points where P_κ only has simple roots. (This is the reason why we have recalled the proof of Lemma 1 in the case where all roots are simple.) We shall eventually glue things together thanks to a suitable partition of unity.

Let us first consider the point $\underline{\kappa}^{(1)} \in (\mathbb{S}^1)^d$ for which $P_{\underline{\kappa}^{(1)}}$ has one multiple root (of multiplicity m_1) in \mathbb{D} and in the neighborhood of which we have a smooth splitting of the eigenmodes z_1, \dots, z_{m_1} . The other roots $z_{m_1+1}, \dots, z_{s+1}$ are simple and can thus be determined holomorphically with respect to κ in the neighborhood of $\underline{\kappa}^{(1)}$. Keeping in mind that the dominant coefficient of the polynomial $P_\kappa(z)$ equals $\widehat{Q}_{s+1}(\kappa)$ (which is nonzero for $\kappa \in (\mathbb{S}^1)^d$), we consider some $\kappa \in (\mathbb{S}^1)^d$ sufficiently close to $\underline{\kappa}^{(1)}$ and introduce the Lagrange polynomials:

$$\forall k = 1, \dots, s+1, \quad P_{k,\kappa}(z) := \widehat{Q}_{s+1}(\kappa) \prod_{\substack{j=1 \\ j \neq k}}^{s+1} (z - z_j(\kappa)).$$

We then introduce the following energy and dissipation Hermitian forms on \mathbb{C}^{s+1} (below, κ always denotes an element of $(\mathbb{S}^1)^d$ that is sufficiently close to $\underline{\kappa}^{(1)}$ so that all considered quantities are well-defined):

$$\forall (w^0, \dots, w^s) \in \mathbb{C}^{s+1},$$

$$\begin{aligned} q_{e,\kappa}(w^0, \dots, w^s) &:= \sum_{k=1}^{s+1} |P_{k,\kappa}(\mathbf{T})w^0|^2 \\ &+ \sum_{k=1}^{m_1} \sum_{j=1}^{m_1-1} \varepsilon^{m_1-j} (1 - |z_k(\kappa)|^2)^{2(m_1-j)} \\ &\times \left| \widehat{Q}_{s+1}(\kappa) (\mathbf{T} - z_k(\kappa))^{j-1} \prod_{\ell=m_1+1}^{s+1} (\mathbf{T} - z_\ell(\kappa)) w^0 \right|^2, \end{aligned} \tag{22}$$

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$$\begin{aligned}
 q_{d,\kappa}(w^0, \dots, w^s) &:= \sum_{k=1}^{s+1} (1 - |z_k(\kappa)|^2) |P_{k,\kappa}(\mathbf{T})w^0|^2 \\
 &+ \sum_{k=1}^{m_1} \sum_{j=1}^{m_1-1} \varepsilon^{m_1-j} (1 - |z_k(\kappa)|^2)^{2(m_1-j)} \\
 &\times \left\{ \left| \widehat{Q}_{s+1}(\kappa)(\mathbf{T} - z_k(\kappa))^{j-1} \prod_{\ell=m_1+1}^{s+1} (\mathbf{T} - z_\ell(\kappa))w^0 \right|^2 \right. \\
 &\quad \left. - \left| \widehat{Q}_{s+1}(\kappa)(\mathbf{T} - z_k(\kappa))^{j-1} \prod_{\ell=m_1+1}^{s+1} (\mathbf{T} - z_\ell(\kappa))w^1 \right|^2 \right\},
 \end{aligned} \tag{23}$$

where $\varepsilon > 0$ is a parameter to be fixed later on. Using the decomposition (13) which we have recalled in the proof of Lemma 1, we have the decomposition

$$\begin{aligned}
 &2\operatorname{Re}\left(\overline{\mathbf{T}(P'_\kappa(\mathbf{T})w^0)}P_\kappa(\mathbf{T})w^0\right) - (s+1)|P_\kappa(\mathbf{T})w^0|^2 \\
 &= (\mathbf{T} - I)(q_{e,\kappa}(w^0, \dots, w^s)) + q_{d,\kappa}(w^0, \dots, w^s),
 \end{aligned} \tag{24}$$

for all vectors $(w^0, \dots, w^s) \in \mathbb{C}^{s+1}$, because we have just added and subtracted some Hermitian forms to the energy-dissipation balance law (13). It remains to prove that $q_{d,\kappa}$ in (23) is nonnegative and that $q_{e,\kappa}$ in (22) is positive definite. Let us start with $q_{e,\kappa}$. If κ does not equal $\underline{\kappa}^{(1)}$, we know from Assumption 2 that the roots $z_1(\kappa), \dots, z_{s+1}(\kappa)$ are pairwise distinct so the Lagrange polynomials $P_{k,\kappa}$ form a basis of $\mathbb{C}_s[X]$. Hence $q_{e,\kappa}$ in (22) is positive definite because we have added a nonnegative form to a positive definite one. We thus now consider the case $\kappa = \underline{\kappa}^{(1)}$ for which the m_1 first roots z_1, \dots, z_{m_1} all collapse to $\underline{z}^{(1)}$ and the m_1 first Lagrange polynomials $P_{1,\underline{\kappa}^{(1)}}, \dots, P_{m_1,\underline{\kappa}^{(1)}}$ are all equal. At the base point $\kappa = \underline{\kappa}^{(1)}$, the definition (22) thus reduces to:

$$\begin{aligned}
 q_{e,\underline{\kappa}^{(1)}}(w^0, \dots, w^s) &= m_1 |P_{1,\underline{\kappa}^{(1)}}(\mathbf{T})w^0|^2 + \sum_{k=m_1+1}^{s+1} |P_{k,\underline{\kappa}^{(1)}}(\mathbf{T})w^0|^2 \\
 &+ m_1 \sum_{j=1}^{m_1-1} \varepsilon^{m_1-j} (1 - |\underline{z}^{(1)}|^2)^{2(m_1-j)} \\
 &\times \left| \widehat{Q}_{s+1}(\underline{\kappa}^{(1)})(\mathbf{T} - \underline{z}^{(1)})^{j-1} \prod_{\ell=m_1+1}^{s+1} (\mathbf{T} - z_\ell(\underline{\kappa}^{(1)}))w^0 \right|^2,
 \end{aligned}$$

which (up to the harmless positive constant m_1 in the second line) coincides with our definition of the Hermitian form in (18). Since the polynomials:

$$\begin{aligned} &P_{1,\underline{\kappa}^{(1)}}(X), P_{m_1+1,\underline{\kappa}^{(1)}}(X), \dots, P_{s+1,\underline{\kappa}^{(1)}}(X), \\ &\widehat{Q}_{s+1}(\underline{\kappa}^{(1)}) \prod_{\ell=m_1+1}^{s+1} (X - z_\ell(\underline{\kappa}^{(1)})), \widehat{Q}_{s+1}(\underline{\kappa}^{(1)})(X - \underline{z}^{(1)}) \prod_{\ell=m_1+1}^{s+1} (X - z_\ell(\underline{\kappa}^{(1)})), \\ &\dots, \widehat{Q}_{s+1}(\underline{\kappa}^{(1)})(X - \underline{z}^{(1)})^{m_1-2} \prod_{\ell=m_1+1}^{s+1} (X - z_\ell(\underline{\kappa}^{(1)})), \end{aligned}$$

form a basis of $\mathbb{C}_s[X]$ (this is again the classical Hermite interpolation problem), the form $q_{\varepsilon,\underline{\kappa}^{(1)}}$ is positive definite as long as the parameter ε is a fixed positive constant (the choice $\varepsilon = 1/8$ that is made below will do). Moreover, once ε is fixed, the form $q_{\varepsilon,\kappa}$ depends in a C^∞ way on κ in the neighborhood of $\underline{\kappa}^{(1)}$.

We now show that the form $q_{d,\kappa}$ in (23) is nonnegative for a well-chosen parameter $\varepsilon > 0$ and $\kappa \in (\mathbb{S}^1)^d$ sufficiently close to $\underline{\kappa}^{(1)}$. The argument is quite similar to what we have done in the proof of Lemma 1 but we now need to take into account that the m_1 first eigenmodes z_1, \dots, z_{m_1} split for $\kappa \neq \underline{\kappa}^{(1)}$, which will make us choose $\varepsilon > 0$ slightly smaller than in the proof of Lemma 1 in order to absorb an additional error. Before going on, let us recall that the eigenmodes $z_1(\kappa), \dots, z_{s+1}(\kappa)$ belong to $\overline{\mathbb{D}}$ for $\kappa \in (\mathbb{S}^1)^d$ close to $\underline{\kappa}^{(1)}$ with $\kappa \neq \underline{\kappa}^{(1)}$. By continuity, this implies that they also belong to $\overline{\mathbb{D}}$ for $\kappa = \underline{\kappa}^{(1)}$. Hereafter, we shall consider $\kappa \in (\mathbb{S}^1)^d$ close to $\underline{\kappa}^{(1)}$ and shall therefore feel free to use the inequality $|z_\ell(\kappa)| \leq 1$ for all $\ell = 1, \dots, s+1$ (the so-called von Neumann condition).

Let us consider some vector $(w^0, \dots, w^s) \in \mathbb{C}^{s+1}$ and let us introduce the notation:

$$\forall k, j = 1, \dots, m_1, \quad W_{k,j} := \widehat{Q}_{s+1}(\kappa) (\mathbf{T} - z_k(\kappa))^{j-1} \prod_{\ell=m_1+1}^{s+1} (\mathbf{T} - z_\ell(\kappa)) w^0, \quad (25)$$

where the complex numbers $W_{k,j}$ (which, according to (25), are linear combinations of w^0, \dots, w^s) also depend on κ but there is no need to keep track of this in what follows. We start from the definition (23) and derive the lower bound:

$$\begin{aligned} q_{d,\kappa}(w^0, \dots, w^s) &\geq \sum_{k=1}^{m_1} (1 - |z_k(\kappa)|^2) |P_{k,\kappa}(\mathbf{T}) w^0|^2 \\ &\quad + \sum_{k=1}^{m_1} \sum_{j=1}^{m_1-1} \varepsilon^{m_1-j} (1 - |z_k(\kappa)|^2)^{2(m_1-j)} \\ &\quad \times \left(|W_{k,j}|^2 - |W_{k,j+1} + z_k(\kappa) W_{k,j}|^2 \right). \end{aligned}$$

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Expanding the square modulus $|W_{k,j+1} + z_k(\kappa)W_{k,j}|^2$ and using Young's inequality under the form:

$$\begin{aligned} \left| 2\operatorname{Re}\left(\overline{z_k(\kappa)W_{k,j}}W_{k,j+1}\right) \right| &\leq \frac{1}{2}(1 - |z_k(\kappa)|^2)|W_{k,j}|^2 + \frac{2|z_k(\kappa)|^2}{1 - |z_k(\kappa)|^2}|W_{k,j+1}|^2 \\ &\leq \frac{1}{2}(1 - |z_k(\kappa)|^2)|W_{k,j}|^2 + \frac{1 + |z_k(\kappa)|^2}{1 - |z_k(\kappa)|^2}|W_{k,j+1}|^2, \end{aligned}$$

we get:

$$\begin{aligned} q_{d,\kappa}(w^0, \dots, w^s) &\geq \sum_{k=1}^{m_1} (1 - |z_k(\kappa)|^2) |P_{k,\kappa}(\mathbf{T})w^0|^2 \\ &\quad + \sum_{k=1}^{m_1} \sum_{j=1}^{m_1-1} \varepsilon^{m_1-j} (1 - |z_k(\kappa)|^2)^{2(m_1-j)} \\ &\quad \times \left(\frac{1 - |z_k(\kappa)|^2}{2} |W_{k,j}|^2 - \frac{2}{1 - |z_k(\kappa)|^2} |W_{k,j+1}|^2 \right). \end{aligned}$$

After shifting indices, we end up with:

$$\begin{aligned} q_{d,\kappa}(w^0, \dots, w^s) &\geq \sum_{k=1}^{m_1} (1 - |z_k(\kappa)|^2) |P_{k,\kappa}(\mathbf{T})w^0|^2 \\ &\quad + \sum_{k=1}^{m_1} \sum_{j=1}^{m_1-1} \frac{\varepsilon^{m_1-j}}{2} (1 - |z_k(\kappa)|^2)^{2(m_1-j)+1} |W_{k,j}|^2 \\ &\quad - \sum_{k=1}^{m_1} \sum_{j=2}^{m_1} 2\varepsilon \varepsilon^{m_1-j} (1 - |z_k(\kappa)|^2)^{2(m_1-j)+1} |W_{k,j}|^2. \end{aligned}$$

Instead of choosing $\varepsilon \in (0, 1/4]$ as in the proof of Lemma 1, we make the more restrictive choice $\varepsilon \in (0, 1/8]$ and thus obtain:

$$\begin{aligned} q_{d,\kappa}(w^0, \dots, w^s) &\geq \sum_{k=1}^{m_1} (1 - |z_k(\kappa)|^2) |P_{k,\kappa}(\mathbf{T})w^0|^2 - \frac{(1 - |z_k(\kappa)|^2)}{4} |W_{k,m_1}|^2 \\ &\quad + \sum_{k=1}^{m_1} \sum_{j=1}^{m_1-1} \frac{\varepsilon^{m_1-j}}{4} (1 - |z_k(\kappa)|^2)^{2(m_1-j)+1} |W_{k,j}|^2. \end{aligned} \quad (26)$$

We go back to the definition of the Lagrange polynomial $P_{k,\kappa}$ and of the complex numbers $W_{k,j}$. For $k = 1, \dots, m_1$, we have:

$$P_{k,\kappa}(z) = \widehat{Q_{s+1}}(\kappa) \prod_{\substack{j=1 \\ j \neq k}}^{m_1} (z - z_j(\kappa)) \prod_{\ell=m_1+1}^{s+1} (z - z_\ell(\kappa)).$$

The goal is to absorb in (26) the only negative term by means of all other positive quantities. To do this, we observe that we can expand the polynomial

$$(X - z_k(\kappa))^{m_1-1},$$

on the basis of $\mathbb{C}_{m_1-1}[X]$ formed by the polynomials:

$$1, (X - z_k(\kappa)), (X - z_k(\kappa))^{m_1-2}, \prod_{\substack{j=1 \\ j \neq k}}^{m_1} (X - z_j(\kappa)).$$

The linear system for determining the coefficients is lower triangular and has determinant 1 so we can write for each $k = 1, \dots, m_1$:

$$(X - z_k(\kappa))^{m_1-1} = \prod_{\substack{j=1 \\ j \neq k}}^{m_1} (X - z_j(\kappa)) + \sum_{j=1}^{m_1-1} a_{k,j}(\kappa) (X - z_k(\kappa))^{j-1}, \quad (27)$$

with holomorphic functions $a_{k,j}$ defined in the neighborhood of $\underline{\kappa}^{(1)}$ and that vanish at $\underline{\kappa}^{(1)}$. The decomposition (27) gives (just use the definition (25) and the expression of the Lagrange polynomial $P_{k,\kappa}$):

$$W_{k,m_1} = P_{k,\kappa}(\mathbf{T})w^0 + \sum_{j=1}^{m_1-1} a_{k,j}(\kappa)W_{k,j},$$

and we now apply the Cauchy-Schwarz inequality twice to get:

$$|W_{k,m_1}|^2 \leq 2|P_{k,\kappa}(\mathbf{T})w^0|^2 + 2(m_1 - 1) \sum_{j=1}^{m_1-1} |a_{k,j}(\kappa)|^2 |W_{k,j}|^2.$$

Fixing from now on $\varepsilon = 1/8$ and using the latter inequality in (26), we find that $q_{d,\kappa}$ is nonnegative for κ sufficiently close to $\underline{\kappa}^{(1)}$ (recall that $|z_k(\kappa)| < 1$ uniformly with respect to κ in the neighborhood of $\underline{\kappa}^{(1)}$ since the multiple eigenvalue $\underline{z}^{(1)}$ lies in \mathbb{D}). Moreover, we observe on the defining equation (23) that the Hermitian form $q_{d,\kappa}$ depends in a C^∞ way on κ in the neighborhood of $\underline{\kappa}^{(1)}$.

The above analysis close to $\underline{\kappa}^{(1)}$ can be repeated word for word in the neighborhood of any other point $\underline{\kappa}^{(2)}, \dots, \underline{\kappa}^{(K)}$ where the dispersion relation (4) has a multiple root. Now, if $\underline{\kappa} \in (\mathbb{S}^1)^d$ is such that the dispersion relation (4) only has simple roots at $\kappa = \underline{\kappa}$, the analysis is much simpler since we know in that case that the roots

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z_1, \dots, z_{s+1} locally depend holomorphically on κ and the energy and dissipation forms can be simply defined as:

$$\begin{aligned} \forall (w^0, \dots, w^s) \in \mathbb{C}^{s+1}, \quad q_{e,\kappa}(w^0, \dots, w^s) &:= \sum_{k=1}^{s+1} |P_{k,\kappa}(\mathbf{T})w^0|^2, \\ q_{d,\kappa}(w^0, \dots, w^s) &:= \sum_{k=1}^{s+1} (1 - |z_k(\kappa)|^2) |P_{k,\kappa}(\mathbf{T})w^0|^2, \end{aligned}$$

with the same notation as above for the Lagrange polynomials $P_{k,\kappa}$. At this stage, we have shown that for any base point $\underline{\kappa}$ in the compact manifold $(\mathbb{S}^1)^d$, there exists an open neighborhood $\underline{\mathcal{V}}$ of $\underline{\kappa}$ in $(\mathbb{S}^1)^d$ and there exists a \mathcal{C}^∞ mapping $q_{e,\kappa}$, resp. $q_{d,\kappa}$, on $\underline{\mathcal{V}}$ with values in the set of positive definite, resp. nonnegative, Hermitian forms, such that the decomposition (24) holds for all $\kappa \in \underline{\mathcal{V}}$ and all vectors $(w^0, \dots, w^s) \in \mathbb{C}^{s+1}$. By compactness of $(\mathbb{S}^1)^d$, we can take a finite covering of $(\mathbb{S}^1)^d$ by such neighborhoods and glue the local definitions of the energy and dissipation forms thanks to a subordinate partition of unity. We have thus constructed a positive definite, resp. nonnegative, Hermitian form $q_{e,\kappa}$, resp. $q_{d,\kappa}$, on \mathbb{C}^{s+1} which depends in a \mathcal{C}^∞ way on $\kappa \in (\mathbb{S}^1)^d$ and such that there holds:

$$\begin{aligned} &2\langle Mv^n, Lv^n \rangle_{-\infty, +\infty} - (s+1) \|Lv^n\|_{-\infty, +\infty}^2 \\ &= (\mathbf{T}-I) \int_{\mathbb{R}^d} q_{e,\kappa}(\widehat{v}^n(\xi), \dots, \widehat{v}^{n+s}(\xi)) \frac{d\xi}{(2\pi)^d} + \int_{\mathbb{R}^d} q_{d,\kappa}(\widehat{v}^n(\xi), \dots, \widehat{v}^{n+s}(\xi)) \frac{d\xi}{(2\pi)^d}, \end{aligned}$$

where we recall that κ is a placeholder for $(\exp(i\xi_1 \Delta x_1), \dots, \exp(i\xi_d \Delta x_d))$. The conclusion of Proposition 2 follows as in Coulombel (2015) by a standard compactness argument for showing continuity of the quadratic forms E and D , and coercivity for E . \square

The \mathcal{C}^∞ regularity of the Hermitian forms $q_{e,\kappa}, q_{d,\kappa}$ with respect to κ is not needed in the proof of Proposition 2 (continuity with respect to κ would be enough) but we have paid attention to that particular issue since it is a crucial step for later extending this construction to variable coefficients problems and applying symbolic calculus rules as in Lax and Nirenberg (1966). This is left to a future work.

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It remains to prove Theorem 1 with the help of Proposition 2. The strategy is exactly the same as in Coulombel (2015) since the analysis in that earlier work shows that the cornerstone of the proof of Theorem 1 is the existence of a multiplier for the

fully discrete Cauchy problem on \mathbb{Z}^d . Let us emphasize that the relation (21) is of the exact same form as in Coulombel (2015). The multiplier Mv^n is the same. The only difference is in the definition of the energy and dissipation forms E and D , but their precise expression is not useful in what follows. What matters is that D is nonnegative, and E is coercive and therefore yields a control of ℓ^2 norms on \mathbb{Z}^d . Hence we can apply the same arguments as in Coulombel (2015) as long as the proof of Theorem 1 only uses the result of Proposition 2 and not the behavior of the roots of the dispersion relation (4). We thus follow the proof of Coulombel (2015, Theorem 1) and explain where the same arguments can be applied without any modification.

3.1 The case with zero initial data

The first step in Coulombel (2015) is to prove the validity of (6) for zero initial data ($f^0 = \dots = f^s = 0$ in (1)). This part of the proof only uses the relation (21) and the fact that the multiplier M has the same stencil as the original difference operator L . Hence we can repeat the arguments in Coulombel (2015) word for word and obtain the validity of (6) when the iteration (1) is considered with zero initial data. It then remains to consider (1) with nonzero initial data in ℓ^2 and zero interior/boundary forcing terms.

3.2 Construction of dissipative boundary conditions

This was the most technical step of the analysis in Coulombel (2015). The goal here is to construct an auxiliary set of numerical boundary conditions for which, with arbitrary initial data in ℓ^2 , we can derive an optimal semigroup estimate and a trace estimate for the solution. Our result here is the same as in Coulombel (2015) but it now holds in the broader framework of Assumption 2. (Theorem 2 is the place where Assumption 3 is needed.)

Theorem 2 – *Let Assumptions 1, 2 and 3 be satisfied. Then for all $P_1 \in \mathbb{N}$, there exists a constant $C_{P_1} > 0$ such that, for all initial data $f^0, \dots, f^s \in \ell^2(\mathbb{Z}^d)$ and for all source term $(g_j^n)_{j_1 \leq 0, j' \in \mathbb{Z}^{d-1}, n \geq s+1}$ that satisfies the integrability condition:*

$$\forall \Gamma > 0, \quad \sum_{n \geq s+1} e^{-2\Gamma n} \sum_{j_1 \leq 0} \|g_{j_1}^n\|_{\ell^2(\mathbb{Z}^{d-1})}^2 < +\infty,$$

there exists a unique sequence $(u_j^n)_{j \in \mathbb{Z}^d, n \in \mathbb{N}}$ in $\ell^2(\mathbb{Z}^d)^{\mathbb{N}}$ solution to the iteration

$$\begin{cases} Lu_j^n = 0, & j \in \mathbb{Z}^d, \quad j_1 \geq 1, \quad n \geq 0, \\ Mu_j^n = g_j^{n+s+1}, & j \in \mathbb{Z}^d, \quad j_1 \leq 0, \quad n \geq 0, \\ u_j^n = f_j^n, & j \in \mathbb{Z}^d, \quad n = 0, \dots, s. \end{cases} \quad (28)$$

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Moreover for all $\gamma > 0$ and $\Delta t \in (0, 1]$, this solution satisfies

$$\begin{aligned} & \sup_{n \geq 0} e^{-2\gamma n \Delta t} \| \| u^n \| \|_{-\infty, +\infty}^2 + \frac{\gamma}{\gamma \Delta t + 1} \sum_{n \geq 0} \Delta t e^{-2\gamma n \Delta t} \| \| u^n \| \|_{-\infty, +\infty}^2 \\ & + \sum_{n \geq 0} \Delta t e^{-2\gamma n \Delta t} \sum_{j_1=1-r_1}^{P_1} \| u_{j_1}^n \|_{\ell^2(\mathbb{Z}^{d-1})}^2 \\ & \leq C_{P_1} \left\{ \sum_{\sigma=0}^s \| \| f^\sigma \| \|_{-\infty, +\infty}^2 + \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \sum_{j_1 \leq 0} \| g_{j_1}^n \|_{\ell^2(\mathbb{Z}^{d-1})}^2 \right\}. \end{aligned} \quad (29)$$

Proof. Unsurprisingly, most of the proof of Theorem 2 is the same as in Coulombel (2015) but there is one specific point where the behavior of the roots to the dispersion relation (4) is used so we review the main steps of the proof and simply refer to Coulombel (2015) when no modification is needed. First, the existence and uniqueness of a solution to (28) follows from the invertibility of Q_{s+1} on $\ell^2(\mathbb{Z}^d)$. Then, using Proposition 1, we can derive the same estimate as in Coulombel (2015) for the solution to (28):

$$\begin{aligned} & \sup_{n \geq 0} e^{-2\gamma n \Delta t} \| \| u^n \| \|_{-\infty, +\infty}^2 + \frac{\gamma}{\gamma \Delta t + 1} \sum_{n \geq 0} \Delta t e^{-2\gamma n \Delta t} \| \| u^n \| \|_{-\infty, +\infty}^2 \\ & + \sum_{n \geq 0} \Delta t e^{-2\gamma(n+s+1)\Delta t} \sum_{j_1 \in \mathbb{Z}} \| Lu_{j_1}^n \|_{\ell^2(\mathbb{Z}^{d-1})}^2 \\ & \leq C \left\{ \sum_{\sigma=0}^s \| \| f^\sigma \| \|_{-\infty, +\infty}^2 + \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \sum_{j_1 \leq 0} \| g_{j_1}^n \|_{\ell^2(\mathbb{Z}^{d-1})}^2 \right\}, \end{aligned} \quad (30)$$

where the constant C is independent of γ , Δt and on the source terms in (28). It remains to derive the trace estimate for the solution (u_j^n) to (28) (that is showing that the third term in the sum on the left hand side of the inequality (29) is controlled by the right hand side).

The derivation of the trace estimate when $\gamma \Delta t$ is large enough is done as in Coulombel (2015) since it only uses the invertibility of the operator Q_{s+1} on $\ell^2(\mathbb{Z}^d)$. We can thus assume from now on $\gamma \Delta t \in (0, \ln R_0]$ for some fixed constant $R_0 > 1$. Then we can deduce from (30) that for any $j_1 \in \mathbb{Z}$, the Laplace-Fourier transform \widehat{u}_{j_1} of the step function

$$u_{j_1} : (t, y) \in \mathbb{R}^+ \times \mathbb{R}^{d-1} \mapsto u_j^n \text{ if } (t, y) \in [n\Delta t, (n+1)\Delta t) \times \prod_{k=2}^d [j_k \Delta x_k, (j_k + 1)\Delta x_k),$$

is well-defined on the half-space $\{\tau \in \mathbb{C}, \operatorname{Re} \tau > 0\} \times \mathbb{R}^{d-1}$. The dual variables to (t, y) are denoted $\tau = \gamma + i\theta$, $\gamma > 0$, and $\eta = (\eta_2, \dots, \eta_d) \in \mathbb{R}^{d-1}$. We also use below

the notation $\eta_\Delta := (\eta_2 \Delta x_2, \dots, \eta_d \Delta x_d)$. The following result, which is proved in Coulombel (2015), is used here as a blackbox since its proof is merely based on the validity of (30) and Plancherel's Theorem.

Lemma 2 – With $R_0 > 1$ fixed as above, there exists a constant $C > 0$ such that for all $\gamma > 0$ and $\Delta t \in (0, 1]$ satisfying $\gamma \Delta t \in (0, \ln R_0]$, there holds

$$\begin{aligned} & \sum_{j_1 \in \mathbb{Z}} \int_{\mathbb{R} \times \mathbb{R}^{d-1}} \left| \sum_{\ell_1 = -r_1}^{p_1} a_{\ell_1}(e^{(\gamma+i\theta)\Delta t}, \eta_\Delta) \widehat{u}_{j_1+\ell_1}(\gamma+i\theta, \eta) \right|^2 d\theta d\eta \\ & + \sum_{j_1 \leq 0} \int_{\mathbb{R} \times \mathbb{R}^{d-1}} \left| \sum_{\ell_1 = -r_1}^{p_1} e^{(\gamma+i\theta)\Delta t} \partial_z a_{\ell_1}(e^{(\gamma+i\theta)\Delta t}, \eta_\Delta) \widehat{u}_{j_1+\ell_1}(\gamma+i\theta, \eta) \right|^2 d\theta d\eta \\ & \leq C \left\{ \sum_{\sigma=0}^s \|f^\sigma\|_{-\infty, +\infty}^2 + \sum_{n \geq s+1} \Delta t e^{-2\gamma n \Delta t} \sum_{j_1 \leq 0} \|g_{j_1, \cdot}^n\|_{\ell^2(\mathbb{Z}^{d-1})}^2 \right\}. \end{aligned} \quad (31)$$

Recall that the functions a_{ℓ_1} , $\ell_1 = -r_1, \dots, p_1$, are defined in (5).

The conclusion now relies on the following crucial result. (This is the place where the behavior of the roots to the dispersion relation (4) matters, and where we therefore need to be careful.)

Lemma 3 (The trace estimate) – Let Assumptions 1, 2 and 3 be satisfied. Let $R_0 > 1$ be fixed as above and let $P_1 \in \mathbb{N}$. Then there exists a constant $C_{P_1} > 0$ such that for all $z \in \mathcal{U}$ with $|z| \leq R_0$, for all $\eta \in \mathbb{R}^{d-1}$ and for all sequence $(w_{j_1})_{j_1 \in \mathbb{Z}} \in \ell^2(\mathbb{Z}; \mathbb{C})$, there holds

$$\begin{aligned} & \sum_{j_1 = -r_1 - P_1}^{P_1} |w_{j_1}|^2 \\ & \leq C_{P_1} \left\{ \sum_{j_1 \in \mathbb{Z}} \left| \sum_{\ell_1 = -r_1}^{p_1} a_{\ell_1}(z, \eta_\Delta) w_{j_1+\ell_1} \right|^2 + \sum_{j_1 \leq 0} \left| \sum_{\ell_1 = -r_1}^{p_1} z \partial_z a_{\ell_1}(z, \eta_\Delta) w_{j_1+\ell_1} \right|^2 \right\}. \end{aligned} \quad (32)$$

As in Coulombel (2015), Lemma 3 yields the conclusion of Theorem 2 by integrating (32) for the sequence $(\widehat{u}_{j_1}(\gamma+i\theta, \eta))_{j_1 \in \mathbb{Z}}$ with respect to (θ, η) (taking $z = e^{(\gamma+i\theta)\Delta t}$ accordingly), using the inequality (31) from Lemma 2 and applying Plancherel's Theorem. We thus focus on the proof of Lemma 3 from now on. \square

Proof (Proof of Lemma 3). We reproduce most of the proof that can already be found in Coulombel (2015) in order to highlight where Assumption 2 (in its new form) is used. We argue by contradiction and assume that the conclusion to Lemma 3 does not hold. Therefore, up to normalizing and extracting subsequences, there exist three sequences (indexed by $k \in \mathbb{N}$):

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- a sequence $(w^k)_{k \in \mathbb{N}}$ with values in $\ell^2(\mathbb{Z}; \mathbb{C})$ such that $(w^k_{-r_1-p_1}, \dots, w^k_{p_1})$ belongs to the unit sphere of $\mathbb{C}^{p_1+r_1+p_1+1}$ for all k , and $(w^k_{-r_1-p_1}, \dots, w^k_{p_1})$ converges towards $(\underline{w}_{-r_1-p_1}, \dots, \underline{w}_{p_1})$ as k tends to infinity,
- a sequence $(z^k)_{k \in \mathbb{N}}$ with values in $\mathcal{U} \cap \{\zeta \in \mathbb{C}, |\zeta| \leq R_0\}$, which converges towards $\underline{z} \in \overline{\mathcal{U}}$,
- a sequence $(\eta^k)_{k \in \mathbb{N}}$ with values in $[0, 2\pi]^{d-1}$, which converges towards $\underline{\eta} \in [0, 2\pi]^{d-1}$,

and these sequences satisfy:

$$\lim_{k \rightarrow +\infty} \sum_{j_1 \in \mathbb{Z}} \left| \sum_{\ell_1=-r_1}^{p_1} a_{\ell_1}(z^k, \eta^k) w^k_{j_1+\ell_1} \right|^2 + \sum_{j_1 \leq 0} \left| \sum_{\ell_1=-r_1}^{p_1} z^k \partial_z a_{\ell_1}(z^k, \eta^k) w^k_{j_1+\ell_1} \right|^2 = 0. \quad (33)$$

We are going to show that (33) implies that the vector $(\underline{w}_{-r_1-p_1}, \dots, \underline{w}_{p_1})$ must be zero, which will yield a contradiction since this vector has norm 1.

• We already know that $(w^k_{-r_1-p_1}, \dots, w^k_{p_1})$ converges towards $(\underline{w}_{-r_1-p_1}, \dots, \underline{w}_{p_1})$ as k tends to infinity, and arguing by induction as in Coulombel (2015), we can show that (33) and Assumption 3 imply that each component $(w^k_{j_1})_{k \in \mathbb{N}}$, $j_1 \in \mathbb{Z}$, has a limit as k tends to infinity. This limit is denoted \underline{w}_{j_1} for any $j_1 \in \mathbb{Z}$. Then (33) implies that the sequence \underline{w} , which does not necessarily belong to $\ell^2(\mathbb{Z}; \mathbb{C})$, satisfies the two recurrence relations (observe that the recurrence relation (35) only holds on $(-\infty, 0)$ and not on \mathbb{Z}):

$$\forall j_1 \in \mathbb{Z}, \quad \sum_{\ell_1=-r_1}^{p_1} a_{\ell_1}(\underline{z}, \underline{\eta}) \underline{w}_{j_1+\ell_1} = 0, \quad (34)$$

$$\forall j_1 \leq 0, \quad \sum_{\ell_1=-r_1}^{p_1} \underline{z} \partial_z a_{\ell_1}(\underline{z}, \underline{\eta}) \underline{w}_{j_1+\ell_1} = 0. \quad (35)$$

• We define the source terms:

$$\forall j_1 \in \mathbb{Z}, \quad F^k_{j_1} := \sum_{\ell_1=-r_1}^{p_1} a_{\ell_1}(z^k, \eta^k) w^k_{j_1+\ell_1}, \quad G^k_{j_1} := \sum_{\ell_1=-r_1}^{p_1} z^k \partial_z a_{\ell_1}(z^k, \eta^k) w^k_{j_1+\ell_1},$$

which, according to (33), satisfy

$$\lim_{k \rightarrow 0} \sum_{j_1 \in \mathbb{Z}} |F^k_{j_1}|^2 = 0, \quad \lim_{k \rightarrow 0} \sum_{j_1 \leq 0} |G^k_{j_1}|^2 = 0. \quad (36)$$

We also introduce the vectors (here T denotes transposition)

$$\forall j_1 \in \mathbb{Z}, \quad W_{j_1}^k := \left(w_{j_1+p_1}^k, \dots, w_{j_1+1-r_1}^k \right)^T, \quad \underline{W}_{j_1} := \left(\underline{w}_{j_1+p_1}, \dots, \underline{w}_{j_1+1-r_1} \right)^T,$$

and the matrices in $\mathcal{M}_{p_1+r_1}(\mathbb{C})$:

$$\mathbb{L}(z, \eta) := \begin{pmatrix} -a_{p_1-1}(z, \eta)/a_{p_1}(z, \eta) & \dots & \dots & -a_{-r_1}(z, \eta)/a_{p_1}(z, \eta) \\ 1 & 0 & \dots & 0 \\ 0 & \ddots & \ddots & \vdots \\ 0 & 0 & 1 & 0 \end{pmatrix}, \quad (37)$$

$$\mathbb{M}(z, \eta) := \begin{pmatrix} -\partial_z a_{p_1-1}(z, \eta)/\partial_z a_{p_1}(z, \eta) & \dots & \dots & -\partial_z a_{-r_1}(z, \eta)/\partial_z a_{p_1}(z, \eta) \\ 1 & 0 & \dots & 0 \\ 0 & \ddots & \ddots & \vdots \\ 0 & 0 & 1 & 0 \end{pmatrix}. \quad (38)$$

The matrix \mathbb{L} is well-defined on $\overline{\mathcal{U}} \times \mathbb{R}^{d-1}$ thanks to Assumption 3. The matrix \mathbb{M} is also well-defined on $\overline{\mathcal{U}} \times \mathbb{R}^{d-1}$ because for any $\eta \in \mathbb{R}^{d-1}$, Assumption 3 asserts that $a_{p_1}(\cdot, \eta)$ is a nonconstant polynomial whose roots lie in \mathbb{D} . From the Gauss-Lucas Theorem, the roots of $\partial_z a_{p_1}(\cdot, \eta)$ lie in the convex hull of those of $a_{p_1}(\cdot, \eta)$, hence in \mathbb{D} . Therefore $\partial_z a_{p_1}(\cdot, \eta)$ does not vanish on $\overline{\mathcal{U}}$. In the same way, $\partial_z a_{-r_1}(\cdot, \eta)$ does not vanish on $\overline{\mathcal{U}}$.

With our above notation, the vectors $W_{j_1}^k, \underline{W}_{j_1}$, satisfy the one step recurrence relations:

$$\forall j_1 \in \mathbb{Z}, \quad W_{j_1+1}^k = \mathbb{L}(z^k, \eta^k) W_{j_1}^k + \left(F_{j_1+1}^k/a_{p_1}(z^k, \eta^k), 0, \dots, 0 \right)^T, \quad (39)$$

$$\underline{W}_{j_1+1} = \mathbb{L}(z, \underline{\eta}) \underline{W}_{j_1}, \quad (40)$$

$$\forall j_1 \leq -1, \quad W_{j_1+1}^k = \mathbb{M}(z^k, \eta^k) W_{j_1}^k + \left(G_{j_1+1}^k/(z^k \partial_z a_{p_1}(z^k, \eta^k)), 0, \dots, 0 \right)^T, \quad (41)$$

$$\underline{W}_{j_1+1} = \mathbb{M}(z, \underline{\eta}) \underline{W}_{j_1}. \quad (42)$$

The recurrence relations (40), (42) are just an equivalent way of writing (34), (35).

- From Assumption 3 and the above application of the Gauss-Lucas Theorem, we already know that both matrices $\mathbb{L}(z, \eta)$ and $\mathbb{M}(z, \eta)$ are invertible for $(z, \eta) \in \overline{\mathcal{U}} \times \mathbb{R}^{d-1}$. Furthermore, a quick analysis shows that $\kappa \in \mathbb{C} \setminus \{0\}$ is an eigenvalue of $\mathbb{L}(z, \eta)$ if and only if z is a solution to the dispersion relation (4). Assumption 2 therefore shows that $\mathbb{L}(z, \eta)$ has no eigenvalue on \mathbb{S}^1 for $(z, \eta) \in \mathcal{U} \times \mathbb{R}^{d-1}$ for otherwise the von Neumann condition would not hold. (This eigenvalue splitting property dates back at least to Kreiss (1968).) However, central eigenvalues on \mathbb{S}^1 may occur for \mathbb{L} when z belongs to \mathbb{S}^1 (see Coulombel (2013) for a thorough analysis of the leap-frog scheme).

3. Semigroup estimates for discrete initial boundary value problems

As in Coulombel (2015), the crucial point for proving Lemma 3 is that Assumption 2 in its new form still precludes central eigenvalues of \mathbb{M} for all $z \in \overline{\mathcal{U}}$. Namely, let us show that for all $z \in \overline{\mathcal{U}}$ and all $\eta \in \mathbb{R}^{d-1}$, $\mathbb{M}(z, \eta)$ has no eigenvalue on \mathbb{S}^1 . This property holds because otherwise, for some $(z, \eta) \in \overline{\mathcal{U}} \times \mathbb{R}^{d-1}$, there would exist a root $\kappa_1 \in \mathbb{S}^1$ to the characteristic polynomial of $\mathbb{M}(z, \eta)$, that is (up to multiplying by a nonzero factor):

$$\sum_{\ell_1=-r_1}^{p_1} z \partial_z a_{\ell_1}(z, \eta) \kappa_1^{\ell_1} = 0.$$

For convenience, the coordinates of η are denoted (η_2, \dots, η_d) . Using the definition (5) of a_{ℓ_1} , and defining $\kappa := (\kappa_1, e^{i\eta_2}, \dots, e^{i\eta_d}) \in (\mathbb{S}^1)^d$, we have found a root $z \in \overline{\mathcal{U}}$ to the relation

$$\sum_{\sigma=1}^{s+1} \sigma \widehat{Q}_\sigma(\kappa) z^{\sigma-1} = 0. \quad (43)$$

This is where the new form of Assumption 2 matters. Namely, we know that for all $\kappa \in (\mathbb{S}^1)^d$, the roots of the polynomial equation (4) lie in $\overline{\mathbb{D}}$ and if there are roots on the boundary \mathbb{S}^1 , then they must necessarily be simple. Applying again the Gauss-Lucas Theorem, we know that the roots to (43) lie in the convex hull of those to (4) and therefore belong to \mathbb{D} (because the only possibility for (43) to have a root on the boundary \mathbb{S}^1 would be that (4) admits a double root on \mathbb{S}^1 but this degeneracy is precluded by Assumption 2). The Gauss-Lucas Theorem thus shows that the roots to the relation (43) do not belong to $\overline{\mathcal{U}}$. Hence $\mathbb{M}(z, \eta)$ has no eigenvalue on \mathbb{S}^1 for any $(z, \eta) \in \overline{\mathcal{U}} \times \mathbb{R}^{d-1}$.

• At this stage, we know that for $(z, \eta) \in \overline{\mathcal{U}} \times \mathbb{R}^{d-1}$, the eigenvalues of $\mathbb{M}(z, \eta)$ split into two groups: those in \mathcal{U} , which we call the unstable ones, and those in \mathbb{D} , which we call the stable ones. For $(z, \eta) \in \overline{\mathcal{U}} \times \mathbb{R}^{d-1}$, we then introduce the spectral projector $\Pi_{\mathbb{M}}^s(z, \eta)$, resp. $\Pi_{\mathbb{M}}^u(z, \eta)$, of $\mathbb{M}(z, \eta)$ on the generalized eigenspace associated with eigenvalues in \mathbb{D} , resp. \mathcal{U} . These projectors are analytic with respect to (z, η) on $\overline{\mathcal{U}} \times \mathbb{R}^{d-1}$. We can integrate from $-\infty$ to 0 the recurrence relation (41) and get

$$\Pi_{\mathbb{M}}^s(z^k, \eta^k) W_0^k = \frac{1}{z^k \partial_z a_{p_1}(z^k, \eta^k)} \sum_{j_1 \leq 0} \mathbb{M}(z^k, \eta^k)^{|j_1|} \Pi_{\mathbb{M}}^s(z^k, \eta^k) \left(G_{j_1}^k, 0, \dots, 0 \right)^T.$$

The projector $\Pi_{\mathbb{M}}^s$ depends analytically on $(z, \eta) \in \overline{\mathcal{U}} \times \mathbb{R}^{d-1}$. Furthermore, since the spectrum of \mathbb{M} does not meet \mathbb{S}^1 for $(z, \eta) \in \overline{\mathcal{U}} \times \mathbb{R}^{d-1}$, there exists a constant $C > 0$ and a parameter $\delta \in (0, 1)$ that are independent of $k \in \mathbb{N}$ and such that

$$\forall j_1 \leq 0, \quad \|\mathbb{M}(z^k, \eta^k)^{|j_1|} \Pi_{\mathbb{M}}^s(z^k, \eta^k)\| \leq C \delta^{|j_1|}.$$

We thus get a uniform estimate with respect to k :

$$|\Pi_{\mathbb{M}}^s(z^k, \eta^k)W_0^k|^2 \leq C \sum_{j_1 \leq 0} |G_{j_1}^k|^2.$$

Passing to the limit and using (36), we get $\Pi_{\mathbb{M}}^s(\underline{z}, \underline{\eta})\underline{W}_0 = 0$, or in other words $\underline{W}_0 = \Pi_{\mathbb{M}}^u(\underline{z}, \underline{\eta})\underline{W}_0$. Furthermore, since $(\underline{W}_{j_1})_{j_1 \leq 0}$ satisfies the recurrence relation (42) with \underline{W}_0 in the generalized eigenspace of $\mathbb{M}(\underline{z}, \underline{\eta})$ associated with eigenvalues in \mathcal{U} , we find that $(\underline{W}_{j_1})_{j_1 \leq 0}$ decays exponentially at $-\infty$ and thus belongs to $\ell^2(-\infty, 0)$.

- The sequence $(\underline{W}_{j_1})_{j_1 \leq 0}$ satisfies both recurrence relations (40) and (42), which equivalently means that the complex valued sequence $(\underline{w}_{j_1})_{j_1 \leq 0}$ satisfies the two recurrence relations (34) and (35) for $j_1 \leq 0$. Hence $(\underline{w}_{j_1})_{j_1 \leq 0}$ satisfies the recurrence relation associated with the greatest common divisor of the polynomials associated with (34) and (35). In other words, the vector \underline{W}_0 belongs to the generalized eigenspace (of either \mathbb{L} or \mathbb{M}) associated with the common eigenvalues of $\mathbb{M}(\underline{z}, \underline{\eta})$ and $\mathbb{L}(\underline{z}, \underline{\eta})$. Since we already know that $\mathbb{M}(\underline{z}, \underline{\eta})$ has no eigenvalue on \mathbb{S}^1 and that \underline{W}_0 belongs to the generalized eigenspace of $\mathbb{M}(\underline{z}, \underline{\eta})$ associated with eigenvalues in \mathcal{U} (the unstable ones), we can conclude that \underline{W}_0 also belongs to the generalized eigenspace of $\mathbb{L}(\underline{z}, \underline{\eta})$ associated with those common eigenvalues of $\mathbb{M}(\underline{z}, \underline{\eta})$ and $\mathbb{L}(\underline{z}, \underline{\eta})$ in \mathcal{U} .

The final argument is the following. The matrix $\mathbb{L}(\underline{z}, \underline{\eta})$ has N^u eigenvalues in \mathcal{U} , N^s in \mathbb{D} and N^c on \mathbb{S}^1 (all eigenvalues are counted with multiplicity). (Since \underline{z} may belong to \mathbb{S}^1 , N^c is not necessarily zero.) With rather obvious notations, we let $\Pi_{\mathbb{L}}^{u,s,c}(z, \eta)$ denote the corresponding spectral projectors of \mathbb{L} for (z, η) sufficiently close to $(\underline{z}, \underline{\eta})$. In particular, the N^u eigenvalues corresponding to $\Pi_{\mathbb{L}}^u(z, \eta)$ lie in \mathcal{U} uniformly away from \mathbb{S}^1 for (z, η) sufficiently close to $(\underline{z}, \underline{\eta})$. We can then integrate (39) from $+\infty$ to 0 and derive (for k sufficiently large):

$$\Pi_{\mathbb{L}}^u(z^k, \eta^k)W_0^k = -\frac{1}{a_{p_1}(z^k, \eta^k)} \sum_{j_1 \geq 0} \mathbb{L}(z^k, \eta^k)^{-j_1-1} \Pi_{\mathbb{L}}^u(z^k, \eta^k) \left(F_{j_1}^k, 0, \dots, 0 \right)^T.$$

Using the uniform exponential decay of $\mathbb{L}(z^k, \eta^k)^{-j_1-1} \Pi_{\mathbb{L}}^u(z^k, \eta^k)$ (with respect to j_1) and the convergence (36), we finally end up with

$$\Pi_{\mathbb{L}}^u(\underline{z}, \underline{\eta})\underline{W}_0 = 0.$$

Since \underline{W}_0 belongs to the generalized eigenspace of \mathbb{L} associated with those common eigenvalues of $\mathbb{M}(\underline{z}, \underline{\eta})$ and $\mathbb{L}(\underline{z}, \underline{\eta})$ in \mathcal{U} , we can conclude that \underline{W}_0 equals zero. Applying the recurrence relation (40), the whole sequence $(\underline{W}_{j_1})_{j_1 \in \mathbb{Z}}$ is zero, which yields the expected contradiction. \square

3.3 End of the proof

The end of the proof of Theorem 1 follows, as in Coulombel (2015), from a superposition argument, see Benzoni-Gavage and Serre (2007, chapter 4) for a similar argument in the context of continuous problems. The solution to (1) with nonzero initial data is decomposed as the sum of a solution to an auxiliary problem (28) (that auxiliary problem incorporates the initial data) and of a solution to a problem of the form (1) with zero initial data (hence our earlier treatment of that case). The analysis in Coulombel (2015) can be applied again word for word so we feel free to refer the reader to that earlier work.

A Numerical schemes with two time levels

As we have seen in the proof of Proposition 2, the construction of energy and dissipation functionals for finite difference operators is dictated, through the Plancherel Theorem, by the analogous construction for recurrence relations. The inconvenience in the proof of Lemma 1 is that the construction of the forms q_e and q_d depends on whether the roots of the polynomial P are simple. There is however one case that can be dealt with in a unified way and for which the coefficients of the forms q_e and q_d depend in a very simple and explicit way on the coefficients of P . Namely, we have the following result in the case of degree two polynomials¹⁰ (the case of degree one polynomials is actually even simpler).

Lemma 4 (Energy-dissipation for second order recurrence relations) – *Let*

$$P := aX^2 + bX + c \in \mathbb{C}[X],$$

be a complex polynomial of degree 2 ($a \neq 0$), that satisfies the following two properties:

- *The two roots of P are located in $\overline{\mathbb{D}}$.*
- *If P has a double root, then it is located in \mathbb{D} .*

Then the Hermitian form q_e , resp. q_d , defined on \mathbb{C}^2 by:

$$\begin{aligned} \forall (x_1, x_2) \in \mathbb{C}^2, \quad q_e(x_1, x_2) &:= 2|a|^2|x_2|^2 + 2\operatorname{Re}(\overline{ax_2}bx_1) + (|a|^2 + |c|^2)|x_1|^2, \\ q_d(x_1, x_2) &:= (|a|^2 - |c|^2)|x_2|^2 + 2\operatorname{Re}(\overline{ax_2}bx_1) - 2\operatorname{Re}(\overline{bx_2}cx_1) \\ &\quad + (|a|^2 - |c|^2)|x_1|^2, \end{aligned}$$

¹⁰Our attempts to obtain an analogue of Lemma 4 with ‘explicit’ Hermitian forms for degree three polynomials have been unsuccessful so far, not mentioning higher degrees.

is positive definite, resp. nonnegative. Furthermore, for any sequence $(v^n)_{n \in \mathbb{N}}$ with values in \mathbb{C} , there holds:

$$\begin{aligned} \forall n \in \mathbb{N}, \quad 2\operatorname{Re}\left(\overline{T(P'(T)v^n)}P(T)v^n\right) \\ = 2|P(T)v^n|^2 + q_e(v^{n+1}, v^{n+2}) - q_e(v^n, v^{n+1}) + q_d(v^n, v^{n+1}). \end{aligned} \quad (44)$$

The defining equations for q_e and q_d in Lemma 4 show that, if P is a polynomial whose coefficients are trigonometric polynomials on \mathbb{R}^d , then the coefficients of q_e and q_d can also be chosen as trigonometric polynomials on \mathbb{R}^d (this is not the case, in general, with our construction in Lemma 1).

Proof. The validity of (44) is a mere algebra exercise. One can for instance expand the left hand side of (44), which reads:

$$2\operatorname{Re}\left(\overline{(2av^{n+2} + bv^{n+1})}(av^{n+2} + bv^{n+1} + cv^n)\right),$$

and verify that it coincides with the right hand side of (44) (a good starting point for this calculation is first to subtract $2|P(T)v^n|^2$ to the latter quantity and factorize $P(T)v^n$ within the real part before expanding). The relation (44) can be also derived by noting that the above forms q_e and q_d in Lemma 4 differ from those given in the proof of Lemma 1 by the standard telescopic “add and subtract” trick. Namely, if z_1, z_2 denote the two roots of P , then q_e equivalently reads:

$$q_e(x_1, x_2) = |a|^2|x_2 - z_2x_1|^2 + |a|^2|x_2 - z_1x_1|^2 + |a|^2(1 - |z_1|^2)(1 - |z_2|^2)|x_1|^2, \quad (45)$$

where the two first terms in the sum on the right hand side of (45) correspond to the Lagrange polynomials $P_1(T)x_1$ and $P_2(T)x_1$, see (14), and the last term on the right hand side of (45) has been added in order to keep q_e positive definite in case the roots z_1 and z_2 coincide. If these roots coincide, then they belong to \mathbb{D} (this last term was absent in Coulombel (2015) since the roots were assumed to be simple). The link with the defining equation for q_e in Lemma 4 is made by using the relations:

$$a(z_1 + z_2) = -b, \quad az_1z_2 = c.$$

It is clear from the above alternative definition (45) that q_e is positive definite under the assumptions we have made for the polynomial P .

Let us now turn to the dissipation form q_d . In agreement with the alternative expression (45) for q_e , the reader can check that the form q_d given in Lemma 4 can be alternatively defined by the expression:

$$\begin{aligned} q_d(x_1, x_2) = |a|^2(1 - |z_1|^2)|x_2 - z_2x_1|^2 + |a|^2(1 - |z_2|^2)|x_2 - z_1x_1|^2 \\ + |a|^2(1 - |z_1|^2)(1 - |z_2|^2)(|x_1|^2 - |x_2|^2), \end{aligned}$$

A. Numerical schemes with two time levels

where the two first terms in the sum on the right hand side read as in (15), and the very last term on the right hand side has been added in order to keep the balance law (44) valid (the “add and subtract” trick). Expanding the square moduli in the expression of q_d , we find that the form q_d can be represented by the Hermitian matrix:

$$|a|^2 \begin{bmatrix} 1 - |z_1|^2 |z_2|^2 & -((1 - |z_1|^2)\bar{z}_2 + (1 - |z_2|^2)\bar{z}_1) \\ -((1 - |z_1|^2)z_2 + (1 - |z_2|^2)z_1) & 1 - |z_1|^2 |z_2|^2 \end{bmatrix},$$

whose trace is clearly nonnegative since z_1 and z_2 belong to $\overline{\mathbb{D}}$. Furthermore, up to the positive $|a|^4$ factor, its determinant equals:

$$(1 - |z_1|^2 |z_2|^2)^2 - |(1 - |z_1|^2)z_2 + (1 - |z_2|^2)z_1|^2.$$

Expanding the square modulus and factorizing, the latter quantity is found to be equivalently given by:

$$(1 - |z_1|^2)(1 - |z_2|^2) \left(1 + |z_1|^2 |z_2|^2 - 2\operatorname{Re}(\bar{z}_2 z_1) \right),$$

which is bounded from below by the nonnegative quantity:

$$(1 - |z_1|^2)^2 (1 - |z_2|^2)^2.$$

Hence the determinant of q_d is nonnegative, so q_d is nonnegative. The proof of Lemma 4 is complete. \square

Lemma 4 has an important consequence for the Cauchy problem (8) with $s = 1$ (finite difference operators with two time levels, as the leap-frog scheme¹¹). Namely, if we follow the proof of Proposition 2 with the aim of constructing some energy and dissipation functionals for (8), we introduce the multiplier M as in (20) and obtain the relation (21). In the case $s = 1$, the polynomial P_κ reads:

$$P_\kappa(X) = \widehat{Q}_2(\kappa)X^2 + \widehat{Q}_1(\kappa)X + \widehat{Q}_0(\kappa),$$

If the Cauchy problem (8) is ℓ^2 -stable, then the polynomial P_κ satisfies the conditions of Lemma 4 for any $\kappa \in (\mathbb{S}^1)^d$. Hence we can apply Lemma 4 and rewrite (21) as:

$$2\langle Mv^n, Lv^n \rangle_{-\infty, +\infty} = 2\|Lv^n\|_{-\infty, +\infty}^2 + E(v^{n+1}, v^{n+2}) - E(v^n, v^{n+1}) + D(v^n, v^{n+1}), \quad (46)$$

¹¹Gustafsson, Kreiss, and Olinger, 1995, *Time dependent problems and difference methods*.

with (here we apply the Plancherel Theorem ‘backwards’):

$$\begin{aligned} E(v^n, v^{n+1}) &:= \int_{\mathbb{R}^d} 2|\widehat{Q_2}(\kappa)|^2 |\widehat{v^{n+1}}(\xi)|^2 + 2\operatorname{Re} \left(\overline{\widehat{Q_2}(\kappa) \widehat{v^{n+1}}(\xi)} \widehat{Q_1}(\kappa) \widehat{v^n}(\xi) \right) \\ &\quad + \left(|\widehat{Q_2}(\kappa)|^2 + |\widehat{Q_0}(\kappa)|^2 \right) |\widehat{v^n}(\xi)|^2 \frac{d\xi}{(2\pi)^d}, \\ &= 2\|Q_2 v^{n+1}\|_{-\infty, +\infty}^2 + 2\langle Q_2 v^{n+1}, Q_1 v^n \rangle_{-\infty, +\infty} \\ &\quad + \|Q_2 v^n\|_{-\infty, +\infty}^2 + \|Q_0 v^n\|_{-\infty, +\infty}^2, \end{aligned}$$

and, similarly:

$$\begin{aligned} D(v^n, v^{n+1}) &:= \|Q_2 v^{n+1}\|_{-\infty, +\infty}^2 - \|Q_0 v^{n+1}\|_{-\infty, +\infty}^2 \\ &\quad + 2\langle Q_2 v^{n+1}, Q_1 v^n \rangle_{-\infty, +\infty} - 2\langle Q_1 v^{n+1}, Q_0 v^n \rangle_{-\infty, +\infty} \\ &\quad + \|Q_2 v^n\|_{-\infty, +\infty}^2 - \|Q_0 v^n\|_{-\infty, +\infty}^2. \end{aligned}$$

The interesting feature of these expressions is that both E and D correspond to the sum, with respect to $j \in \mathbb{Z}^d$, of *local energy* and dissipation densities $E_j(v^n, v^{n+1})$, resp. $D_j(v^n, v^{n+1})$, which depend on *finitely many* values of the sequences v^n, v^{n+1} near j . For instance, the local density $E_j(v^n, v^{n+1})$ can be defined by:

$$E_j(v^n, v^{n+1}) := 2|Q_2 v_j^{n+1}|^2 + 2(Q_2 v_j^{n+1})(Q_1 v_j^n) + |Q_2 v_j^n|^2 + |Q_0 v_j^n|^2.$$

Hence there is now a genuine hope to extend the definition of E and D to more general domains by means of sums of local quantities which do not rely on the Fourier transform, and/or to take the energy-dissipation balance law (46) as a starting point for deriving stability estimates for finite volume space discretizations on unstructured meshes. This is left to a future work.

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